Installation and Operation Manual
P/N 1005172, Rev. C
August 2008

Micro Motion®
Model D and DT Sensors

Instruction Manual

Micro Motion®

EMERSON™
Process Management

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Before You Begin

Your new sensor

Your new Micro Motion® Model D or DT sensor, or D600 sensor and booster amplifier, is one part of a Coriolis flowmetering system. The other part is a transmitter.

Transmitter connections

Model D sensors are available with a factory-supplied 9-wire junction box for connecting to a remotely mounted transmitter, or to a remotely mounted core processor.

Model DT sensors are available with a 3-foot (1-meter) pigtail of cable that connects to a user-supplied junction box. The junction box connects to a remotely mounted transmitter, or to a remotely mounted core processor.

The D600 has a booster amplifier. The booster amplifier is available with a factory-supplied 9-wire junction box for connecting to a remotely mounted transmitter, or with a factory-supplied core processor for connecting to a 4-wire remotely mounted transmitter or to a user-supplied remote host.

All Model D and DT sensors may be connected to the Micro Motion transmitters listed in Table 1. The D600 sensor may be connected to the transmitters listed in Table 2.

Table 1. Transmitter and sensor compatibility guide

Transmitter	Model D sensor (factory-supplied junction box)	Model DT sensor (user-supplied junction box)
Model 1700/2700 (9-wire)	X	X
Model 3500/3700 (9-wire)	X	X
RFT9739 (7- or 9-wire)	X	X
IFT9701 (9-wire)	X(1)	
RFT9712 (7- or 9-wire)	X	X

(1)Except D600.

The D600 sensor and booster amplifier are available in any of the configurations described in Table 2. Table 2 also lists the transmitters that can be used with each configuration.

Table 2. D600 configurations and compatible transmitters

D600 sensor configuration			
Booster amplifier location	**Booster amplifier wiring component**	**Connection to transmitter**	**Compatible transmitters**
Integral to sensor	Junction box	9-wire	• Model 1700/2700 (with integral core processor) • Model 3500/3700 (9-wire) • RFT9739 • RFT9712 • Remote core processor
	Core processor	4-wire	• Model 1700/2700 • Model 3500/3700 (MVD) • Model 2500 • Direct host(1)
Remote from sensor	Junction box	9-wire	• Model 1700/2700 (with integral core processor) • Model 3500/3700 (9-wire) • RFT9739 • RFT9712 • Remote core processor
	Core processor	4-wire	• Model 1700/2700 • Model 3500/3700 (MVD) • Model 2500 • Direct host(1)

(1)A direct host is a user-supplied remote controller, PLC, or other device.

European installations

This Micro Motion product complies with all applicable European directives when properly installed in accordance with the instructions in this quick reference guide. Refer to the EC declaration of conformity for directives that apply to this product.

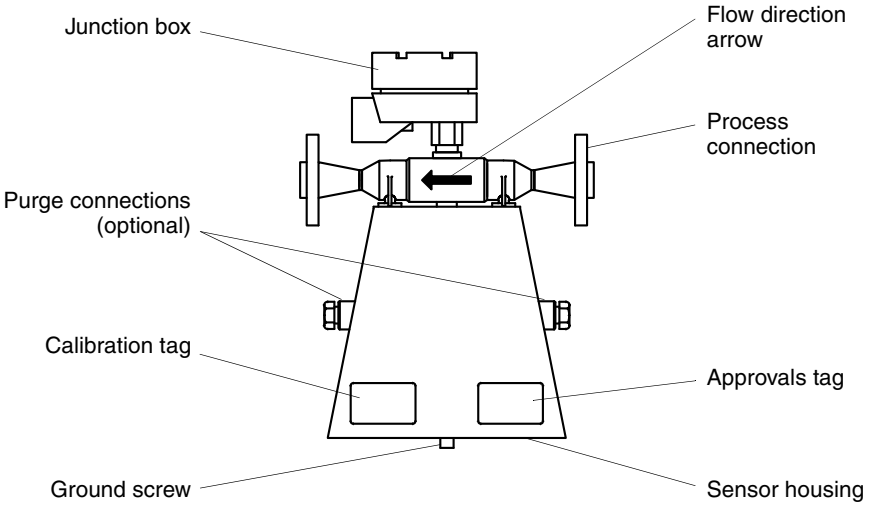
The EC declaration of conformity, with all applicable European directives, and the complete *ATEX Installation Drawings and Instructions* are available on the internet at www.micromotion.com/atex or through your local Micro Motion support center.

Information affixed to equipment that complies with the Pressure Equipment Directive can be found on the internet at www.micromotion.com/library.

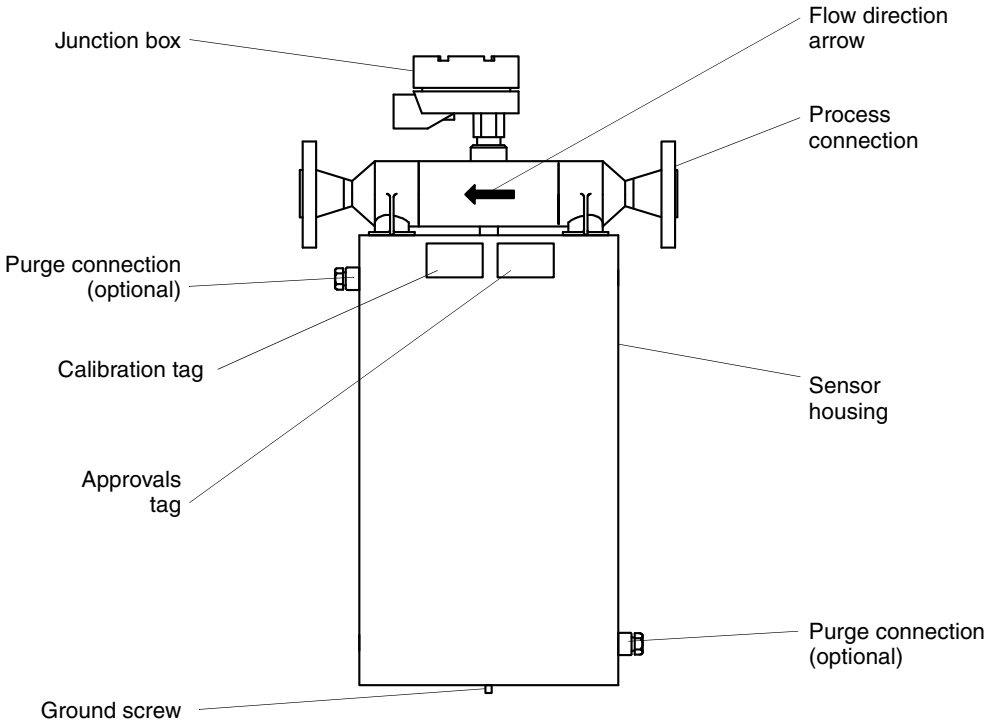
Sensor components

Components of the sensor are illustrated on pages 3-6.

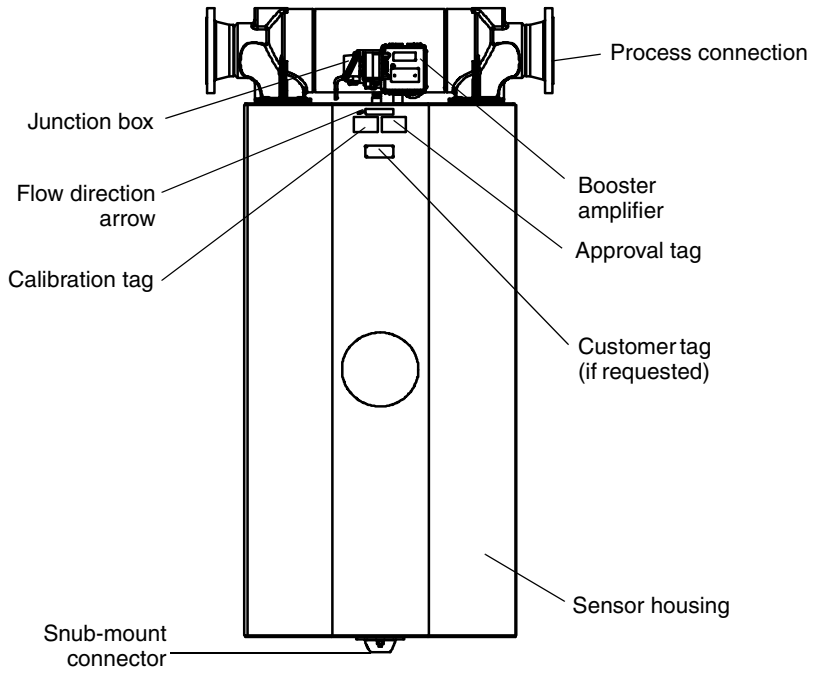
DS025, DH025, DH038, and DS040 sensors



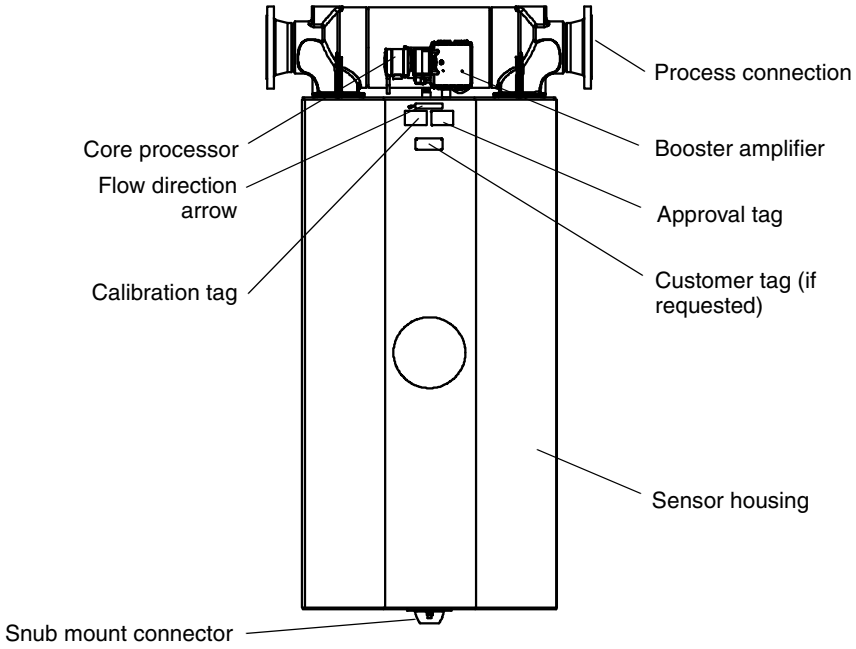
DS065, DS100, DH100, DS150, DH150, DS300, and DH300 sensors



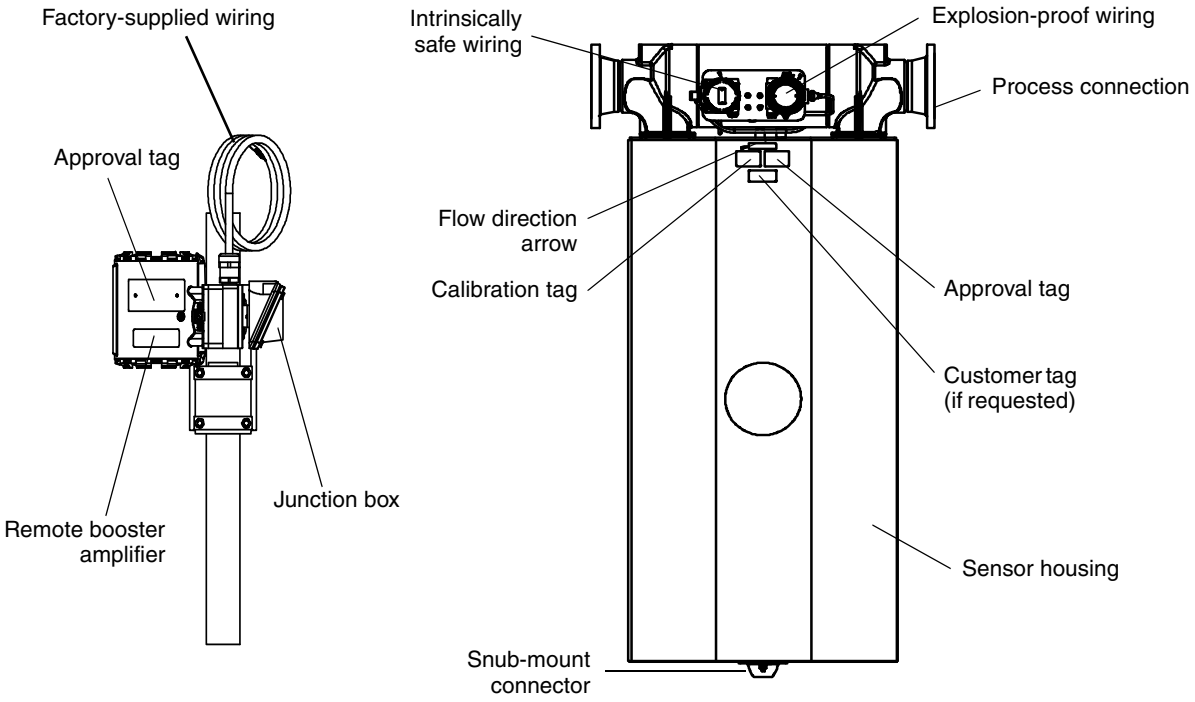
D600 sensor with integral booster amplifier and junction box



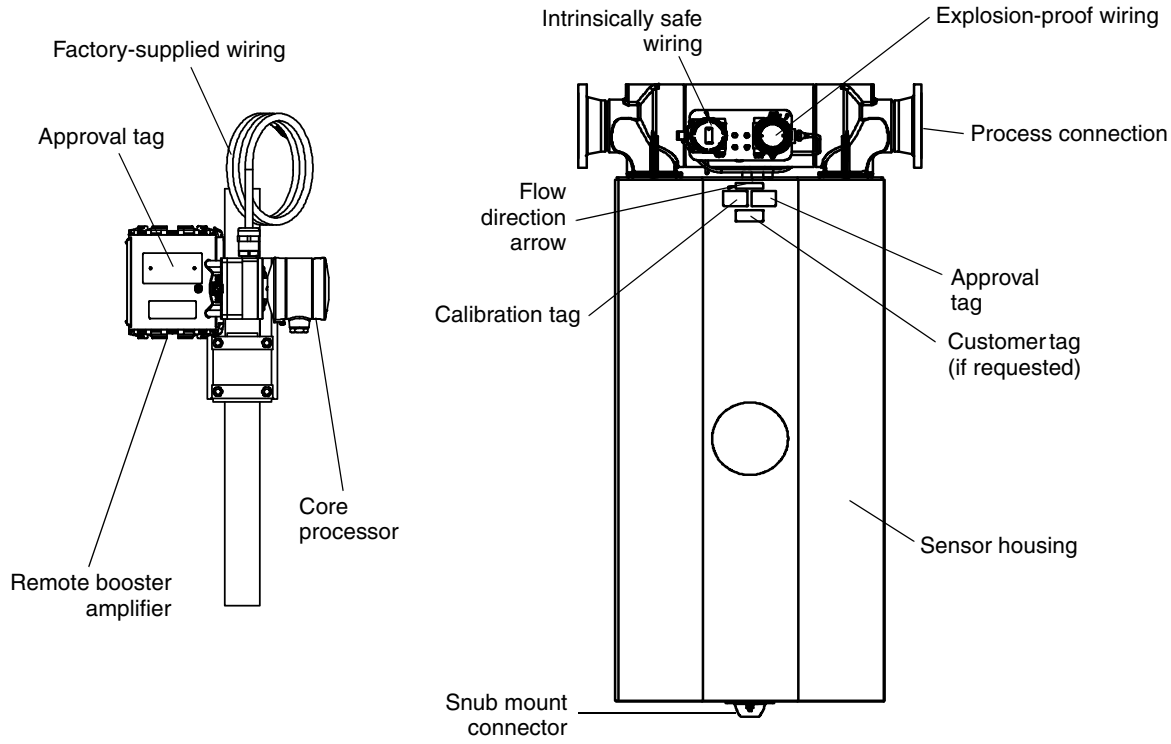
D600 sensor with integral booster amplifier and core processor



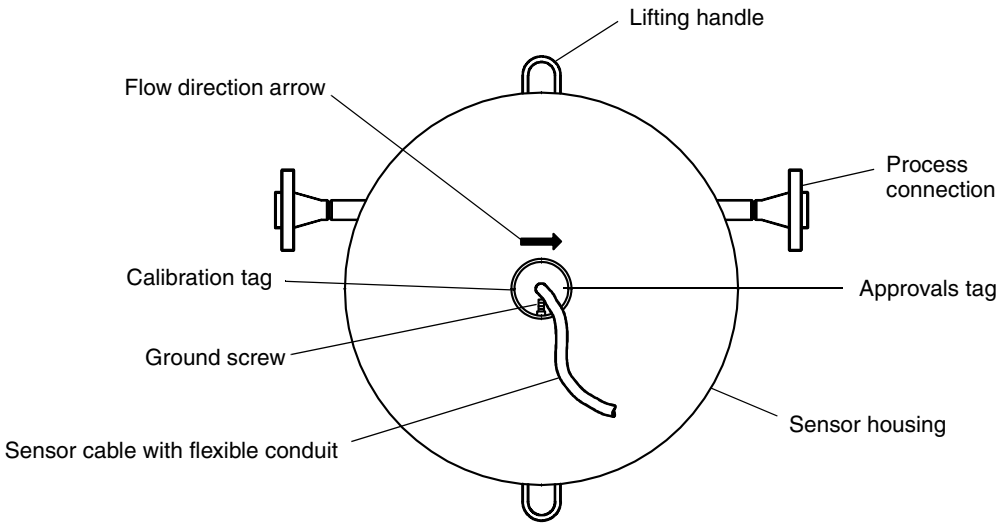
D600 sensor with remote booster amplifier and junction box



D600 sensor with remote booster amplifier and core processor



DT065, DT100, and DT150 sensors



The installation process

Installing your new sensor involves five steps:

Step 1. Location
Determining the proper location for the sensor, taking into account hazardous areas, process piping, transmitter location, and valves. See page 9.

Step 2. Orientation
Determining the desired orientation for the sensor in the process pipeline. See page 13.

Step 3. Mounting
Installing the sensor in the pipeline. See page 17.

Step 4. Wiring
Connecting the flowmeter cable to the sensor and transmitter. See page 19.

Step 5. Startup
Requirements for flowmeter startup. See page 39.

Additional information

In addition to installation instructions, the following subjects are also covered in this manual:

- **Troubleshooting** for problems that might be attributable to the sensor begins on page 41.
- **Purge fittings** are described in Appendix A, page 55.
- **Rupture disks** are discussed in Appendix B, page 59.
- **Maintenance of labels** is covered in Appendix C, page 61.
- **Return policy** for Micro Motion equipment is described in Appendix D, page 65.

Location

Keys for sensor location
The sensor may be located anywhere in the process line, as long as the following conditions are met:

- Before operation, you must be able to stop flow through the sensor. (During the zeroing procedure, flow must be stopped completely, and the sensor must be full of process fluid.)
- The sensor must be installed in an area that is compatible with the classification specified on the sensor approvals tag. (See illustrations, pages 3-6.)

Pipe run

Micro Motion sensors do not require a straight run of pipe upstream or downstream.

Maximum wiring distances

Use these guidelines for calculating maximum wiring distances. Maximum distance between sensor and transmitter depends on cable type. See Table 1.

Table 1. Maximum cable lengths

Cable type	Wire gauge	Maximum length
Micro Motion 9-wire to an MVD transmitter or core processor	Not applicable	60 feet (20 meters)
Micro Motion 9-wire to all other transmitters	Not applicable	1000 feet (300 meters)
Micro Motion 4-wire	Not applicable	1000 feet (300 meters)
User-supplied 4-wire(1)		
• Power wires (VDC)	22 AWG (0,35 mm^2)	300 feet (90 meters)
	20 AWG (0,5 mm^2)	500 feet (150 meters)
	18 AWG (0,8 mm^2)	1000 feet (300 meters)
• Signal wires (RS-485)	22 AWG (0,35 mm^2) or larger	1000 feet (300 meters)

(1)Micro Motion recommends using Micro Motion cable.

DT sensor junction box

Model DT sensors come with a 3-foot (1 meter) pigtail of cable pre-installed. A junction box can be installed at the end of this pigtail.

Environmental limits

Sensor temperature limits

Temperature limits vary by sensor; refer to Table 2.

Table 2. Temperature specifications

Sensor type	°F	°C
DS025	–400 to +350	–240 to +177
DS040	–400 to +350	–240 to +177
DS065	–400 to +350	–240 to +177
DS100	–400 to +400	–240 to +204
DS150	–400 to +400	–240 to +204
DS150Z	+32 to +250	0 to +121
DS300	–400 to +400	–240 to +204
DS300Z	+32 to +250	0 to +121
DH025	–400 to +350	–240 to +177
DH038	–400 to +350	–240 to +177
DH100	–400 to +400	–240 to +204
DH150	–400 to +400	–240 to +204
DH300	–400 to +400	–240 to +204
DT065	+32 to +800	0 to +426
DT100	+32 to +800	0 to +426
DT150	+32 to +800	0 to +426
D600 with integral booster amplifier	–58 to +140	–50 to +60
D600 with remote booster amplifier	–400 to +400	–240 to +200

For ATEX approvals, process fluid temperature can be further restricted by ambient temperatures. For guidelines, go to www.micromotion.com/atex.

D600 booster amplifier ambient temperature limits

Install the booster amplifier in a location that falls within the following limits:

Ambient temperature limits between –58 to +140°F (–50 to +60°C).

For ATEX approvals, process fluid temperature can be further restricted by ambient temperatures. For guidelines, go to www.micromotion.com/atex.

Valves

After the sensor and transmitter have been fully installed, you must perform the zeroing procedure. During the zeroing procedure, flow through the sensor must be halted and the sensor tubes must be completely full of process fluid. A shutoff valve, downstream from the sensor, is required to halt flow during the zeroing procedure. For more information about zeroing, see page 39.

Hazardous area installations

Make sure the hazardous area specified on the sensor approvals tag is suitable for the environment in which the sensor is installed. (See illustrations on pages 3-6.) For installation in an area that requires intrinsic safety, refer to Micro Motion hazardous approval documentation, shipped with the sensor or available from the Micro Motion web site.

For hazardous installations in Europe, refer to standard EN 60079-14 if national standards do not apply.

If you don't have access to the World Wide Web, you can obtain an I.S. manual by contacting the Micro Motion Customer Service Department:

- In the U.S.A., phone **1-800-522-MASS** (1-800-522-6277), 24 hours
- In Canada and Latin America, phone +1 303-527-5200 (U.S.A.)
- In Asia, phone +65 6777-8211 (Singapore)
- In the U.K., phone 0870 240 1978 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 555 (The Netherlands)

Orientation

Keys for sensor orientation
The sensor will function properly in any orientation if the sensor flow tubes remain filled with process fluid.

Flow direction

Micro Motion sensors measure accurately regardless of flow direction as long as the sensor flow tubes remain filled with process fluid.

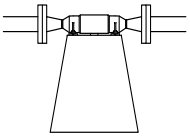
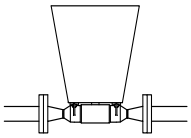
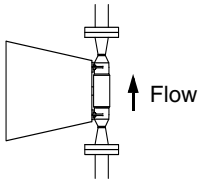
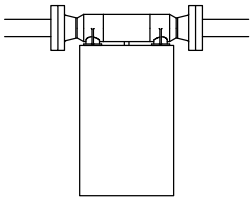
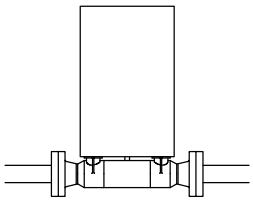
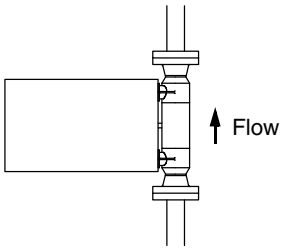
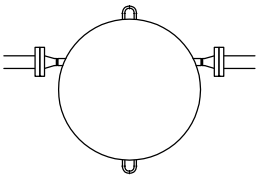
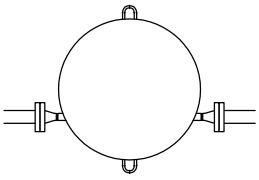
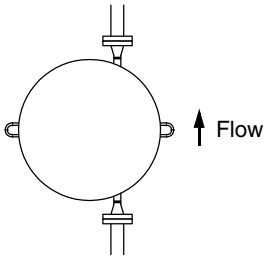
Flow direction arrow
The sensor has a flow direction arrow (see illustrations, pages 3-6) to help you configure the transmitter for flow direction. Process fluid flowing in the direction opposite to the flow direction arrow may cause unexpected transmitter output unless the transmitter is configured appropriately. For instructions on configuring the transmitter's flow direction parameter, refer to the transmitter instruction manual.

Vertical pipeline
If the sensor is installed in a vertical pipeline, liquids and slurries should flow upward through the sensor. Gases may flow upward or downward.

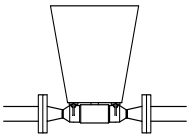
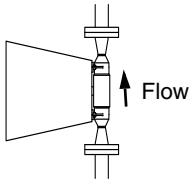
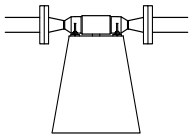
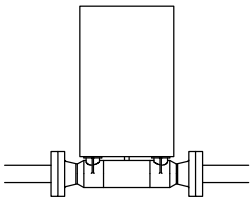
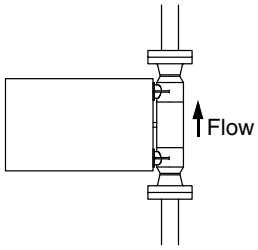
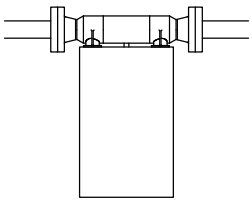
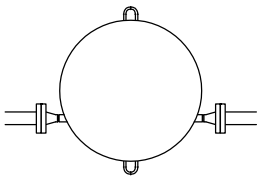
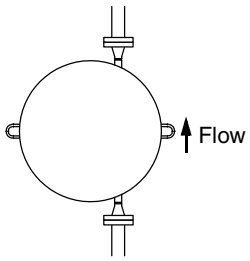
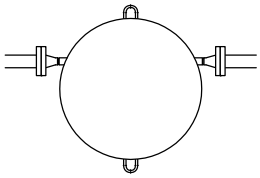
Process fluid

Typical sensor orientations are shown in the tables on the following pages:
- For measuring liquids, see page 14.
- For measuring gases, see page 15.
- For measuring slurries, see page 16.

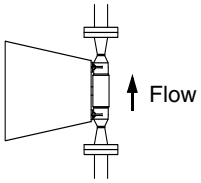
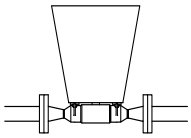
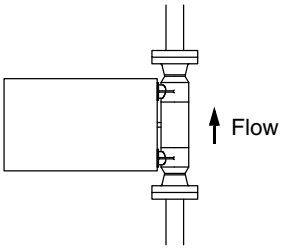
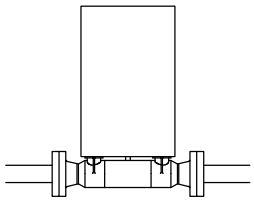
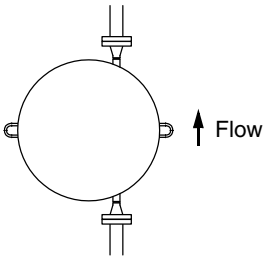
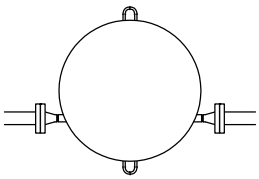
Orientations for measuring liquids

Sensor model	Preferred orientation for measuring liquids	Alternative orientation for measuring liquids	
DS025 **DH025** **DH038** **DS040**	Tubes down Horizontal pipeline 	Tubes up Horizontal pipeline Self-draining 	Flag mount Vertical pipeline 
DS065 **DS100** **DH100** **DS150** **DH150** **DS300** **DH300** **D600**	Tubes down Horizontal pipeline 	Tubes up Horizontal pipeline Self-draining 	Flag mount Vertical pipeline 
DT65 **DT065** **DT100** **DT150**	Tubes down Horizontal pipeline 	Tubes up Horizontal pipeline Self-draining 	Flag mount Vertical pipeline 

Orientations for measuring gases

Sensor model	Preferred orientation for measuring gases	Alternative orientation for measuring gases	
DS025 **DH025** **DH038** **DS040**	Tubes up Horizontal pipeline Self-draining 	Flag mount Vertical pipeline 	**Dry gases only** Tubes down Horizontal pipeline 
DS065 **DS100** **DH100** **DS150** **DH150** **DS300** **DH300** **D600**	Tubes up Horizontal pipeline Self-draining 	Flag mount Vertical pipeline 	**Dry gases only** Tubes down Horizontal pipeline 
DT65 **DT065** **DT100** **DT150**	Tubes up Horizontal pipeline Self-draining 	Flag mount Vertical pipeline 	**Dry gases only** Tubes down Horizontal pipeline 

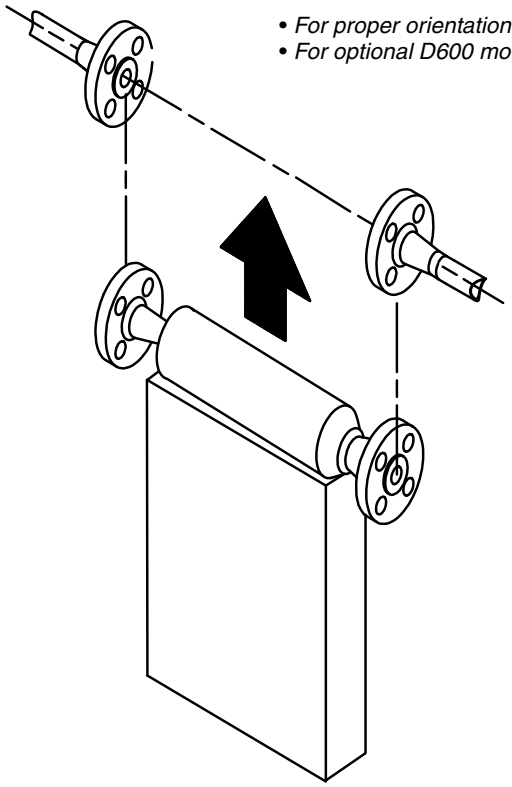
Orientations for measuring slurries

Sensor model	Preferred orientation for measuring slurries	Alternative orientation for measuring slurries
DS025 **DH025** **DH038** **DS040**	Flag mount Vertical pipeline 	Tubes up Horizontal pipeline Self-draining 
DS065 **DS100** **DH100** **DS150** **DH150** **DS300** **DH300** **D600**	Flag mount Vertical pipeline 	Tubes up Horizontal pipeline Self-draining 
DT65 **DT065** **DT100** **DT150**	Flag mount Vertical pipeline 	Tubes up Horizontal pipeline Self-draining 

Mounting

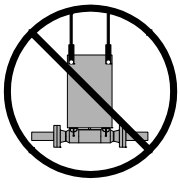
Keys for sensor mounting
Use your common piping practices to minimize:
- Torque on process connections
- Bending load on process connections

Mounting any D or DT sensor



- *For proper orientation, see pages 14-16*
- *For optional D600 mounting, see page 18*

⚠ CAUTION



Using the sensor to support piping can damage the sensor or cause measurement error.

Do not use sensor to support pipe.

Conduit openings

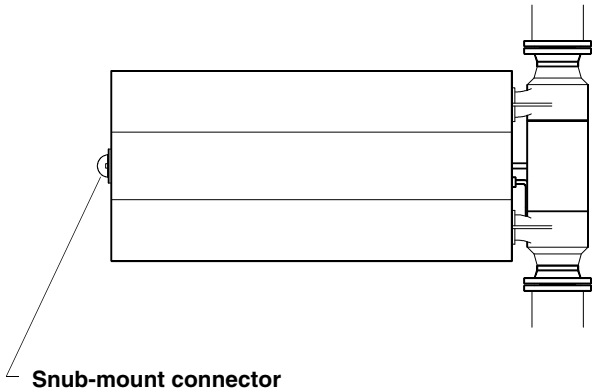
If possible, install wiring with the conduit openings pointed downward to reduce the risk of condensation or excessive moisture in the housing. Otherwise, install drip legs on the cable or conduit.

Optional Model D600 mounting

When installing a Model D600 in a high-vibration area, additional support may be added if desired. Use the D600 snub-mount connector with vibration isolator to help support the sensor. See illustration, below. Typically, the snub-mount connector is used when the D600 is installed in the flag-mount orientation (in a vertical pipeline), as shown below.

Model D600 mounting with snub-mount connector

D600 in flag-mount orientation can use snub connector for added support in high-vibration installations



Snub-mount connector
- Connect support only to the factory-supplied rubber snub-mount connector
- Attach with 1/2"-13 UNC bolt
- Bolt may penetrate isolator to 1 1/2" (40 mm)

DT sensors

Model DT sensors come with a 3-foot (1-meter) pigtail of cable pre-installed. A junction box can be connected at the end of this pigtail. The junction box is used for connecting the cable from the transmitter.

Wiring

Hazardous area installations

The following warning applies to hazardous area installations

⚠ WARNING

Failure to comply with requirements for intrinsic safety in a hazardous area could result in an explosion.

- Make sure the hazardous area specified on the sensor approvals tag is suitable for the environment in which the sensor is installed. See illustrations, pages 3-6.
- For installation in an area that requires intrinsic safety, refer to Micro Motion hazardous approval installation instructions.
- For hazardous area installations in Europe, refer to standard EN 60079-14 if national standards do not apply.

Model D sensor junction box

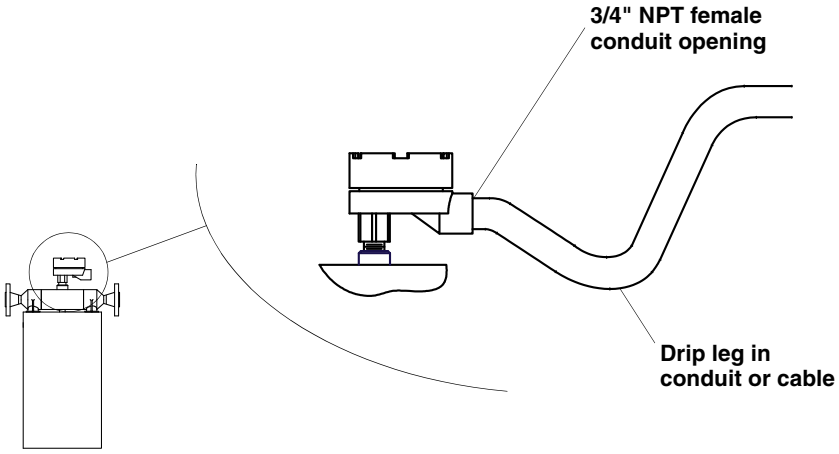
Most Model D sensors are shipped with a junction box for wiring. There are two types of junction boxes: one for the D600 sensor, one for all the other D sensors.

- The D600 junction box is different than the junction box for other D sensors. D600 sensors are also available with a core processor. For more information on the D600 sensor, see page 24.
- Model DT sensors can use a junction box. For more information on the DT sensor junction box, see page 20.

For Model D sensors (except the DT series and D600):

- If it if not already installed, install the junction box on the sensor, following the wiring instructions on the junction box.
- If possible, install wiring with the junction-box opening pointed downward, or with a drip leg in the conduit or cable, to reduce the risk of condensation or excessive moisture in the junction box. See illustration on page 20.
- Next, follow the guidelines in *Connecting and shielding 9-wire cable* to wire the sensor to the transmitter.

Model D sensor junction box



Model DT sensor cable and junction box

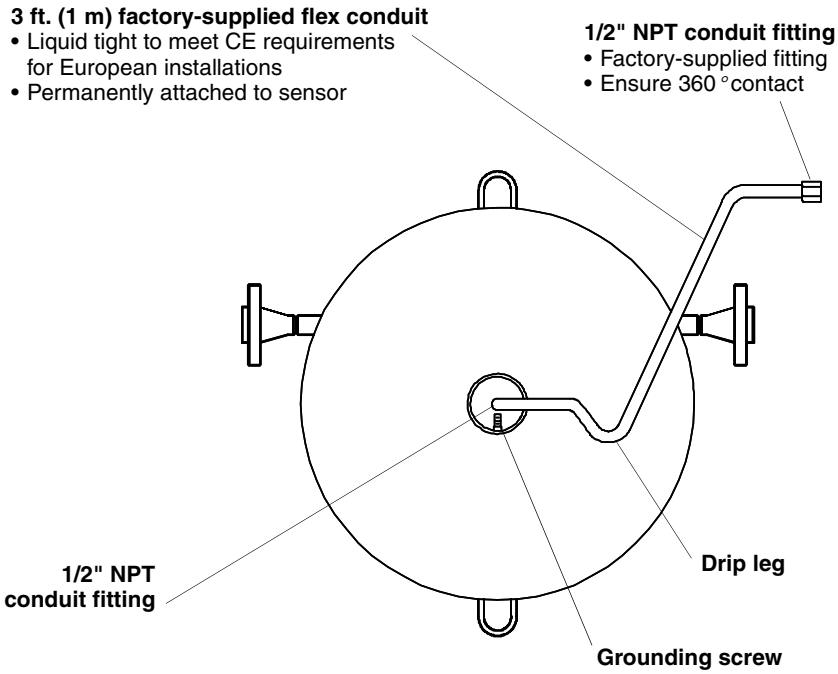
Model DT sensors can use a junction box. Model DT sensors come with a 3-foot (1 meter) pigtail of pre-installed cable and a 3-foot (1 meter) piece of conduit that needs to be fitted over the pre-installed cable. See illustration on page 21.

- Slide the conduit over the pre-installed cable.
- Screw the conduit fitting end into the sensor.

The other end of the conduit can be connected to a user-supplied junction box or directly to a transmitter.

- If the conduit is connected to a user-supplied junction box, connect the wires to the terminals on the junction box. If possible, install wiring with junction-box openings pointed downward, or with drip legs in the conduits or cables, to reduce the risk of condensation or excessive moisture in the junction box. Next, connect the 9-wire cable from the junction box to the transmitter by following the instructions in *Connecting and shielding 9-wire cable*.
- If the conduit is connected directly to a transmitter, refer to the wiring instructions in the transmitter Quick Reference Guide.

Model DT sensor cable


3 ft. (1 m) factory-supplied flex conduit
• Liquid tight to meet CE requirements for European installations
• Permanently attached to sensor
1/2" NPT conduit fitting
• Factory-supplied fitting
• Ensure 360 ° contact
1/2" NPT conduit fitting
Drip leg
Grounding screw

Connecting and shielding 9-wire cable

A 9-wire connection is required between the junction box and the core processor or transmitter. Micro Motion offers two types of 9-wire cable:

- Shielded
- Armored

Both cable types contain shield drain wires. You may also use jacketed cable with conduit.

Cable connections to sensor and transmitter

The wiring procedure is the same for the sensor and transmitter. Refer to the wiring diagrams on the following pages, and follow these steps:

⚠ CAUTION

Failure to seal the sensor and transmitter housings could cause a short circuit, which would result in measurement error or flowmeter failure.

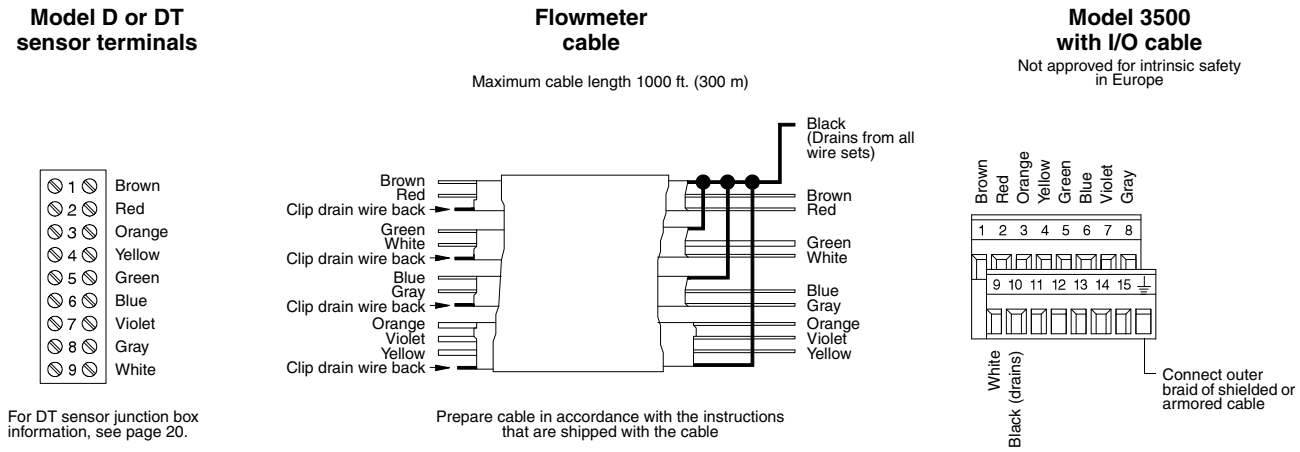
- Ensure integrity of gaskets and O-rings.
- Grease all O-rings before sealing.
- Install drip legs in cable or conduit.
- Seal all conduit openings.

1. Locate the wires by color and terminal number.
2. Insert the stripped ends of the individual wires into the terminal blocks. No bare wires should remain exposed.
   - At the sensor, connect wiring inside the junction box.
   - At the transmitter, connect wiring to the transmitter's intrinsically safe terminals for sensor wiring.
3. Tighten the screws to hold the wires in place.
4. Ensure integrity of gaskets, then tightly close and seal the junction-box cover and all housing covers on the transmitter.

⚠ CAUTION

Drain wires from a 9-wire cable must be clipped at the sensor end and insulated with heat-shrink wrapping. Failure to properly terminate drain wires will cause sensor error.

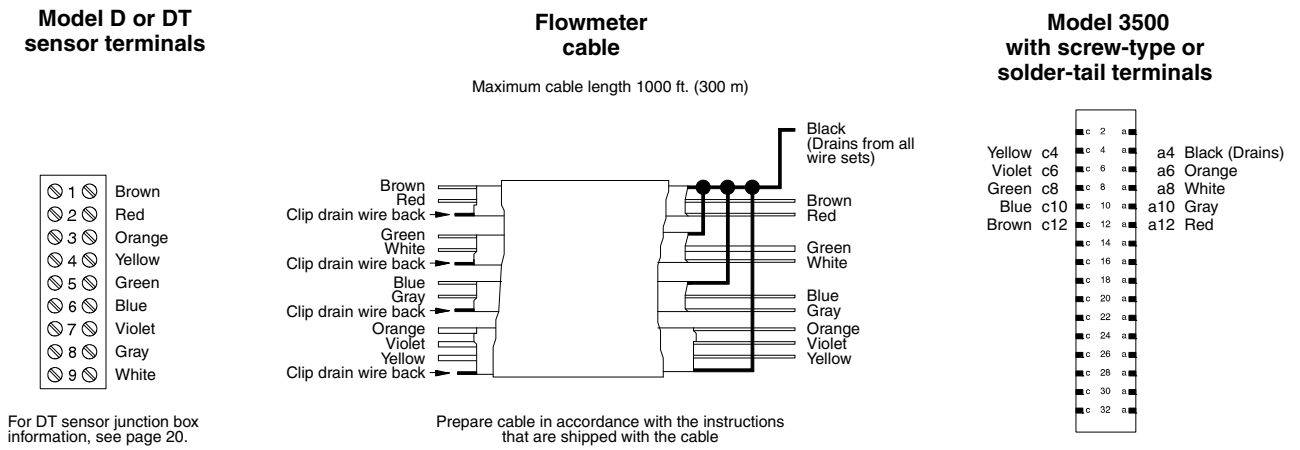
Model D or DT sensor (except D600) wiring to Model 3500 with I/O cable



For DT sensor junction box information, see page 20.

Prepare cable in accordance with the instructions that are shipped with the cable

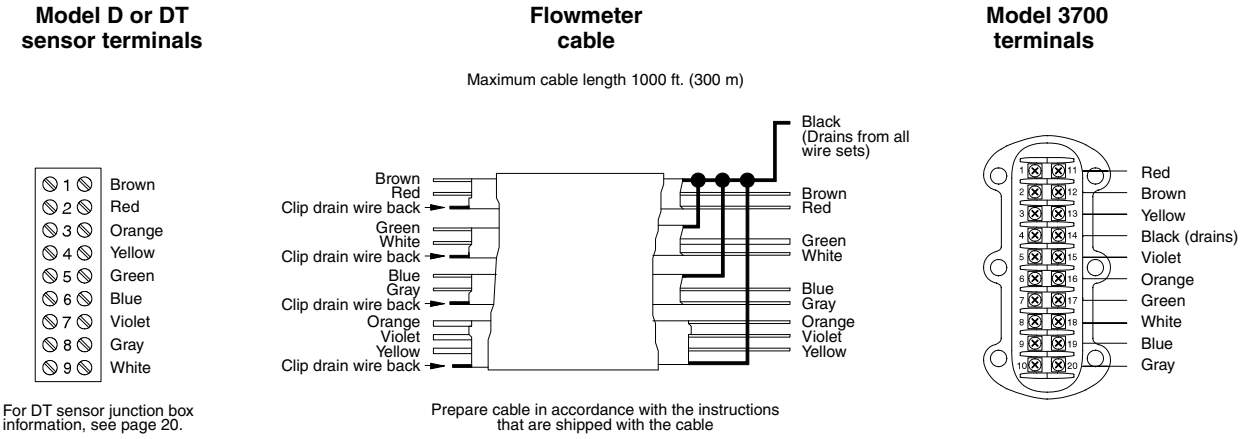
Model D or DT sensor (except D600) wiring to Model 3500 with screw or solder terminals



For DT sensor junction box information, see page 20.

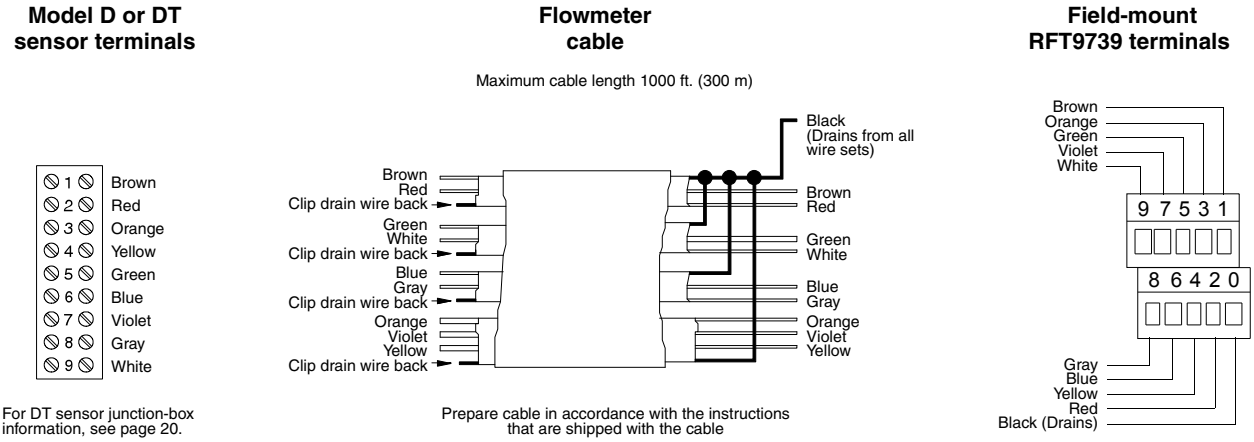
Prepare cable in accordance with the instructions that are shipped with the cable

Model D or DT sensor (except D600) wiring to Model 3700



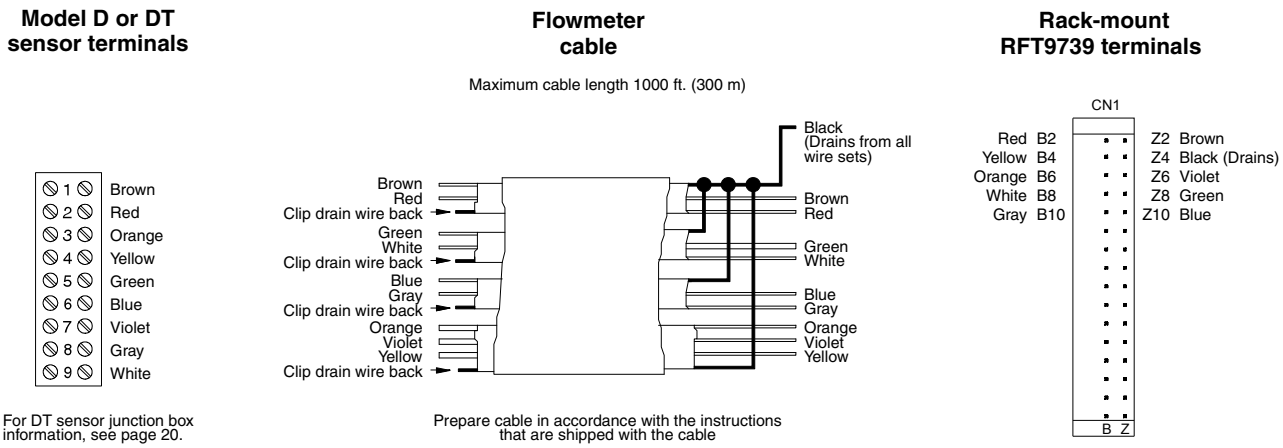
For DT sensor junction box information, see page 20.

Model D or DT sensor (except D600) wiring to RFT9739 field-mount transmitter



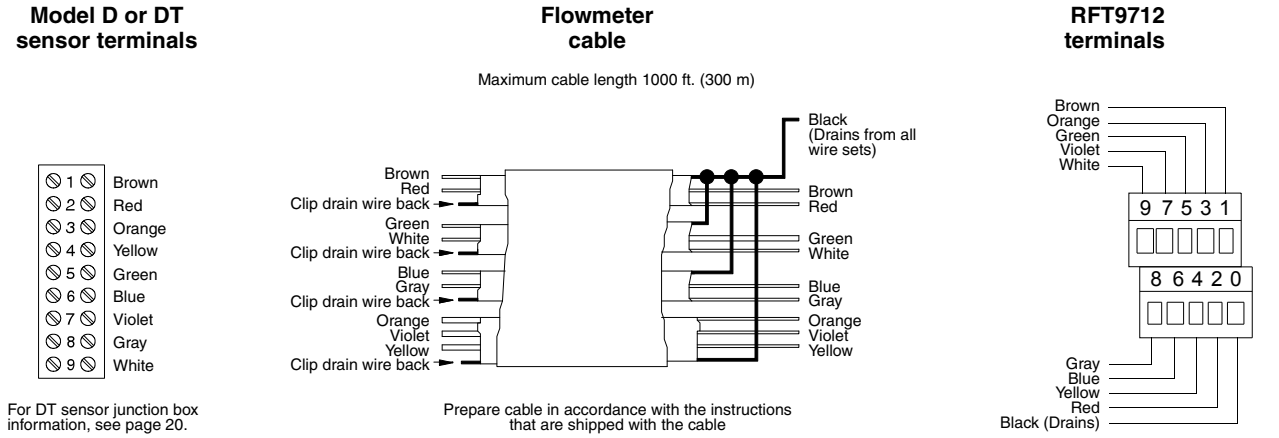
For DT sensor junction-box information, see page 20.

Model D or DT sensor (except D600) wiring to RFT9739 rack-mount transmitter



For DT sensor junction box information, see page 20.

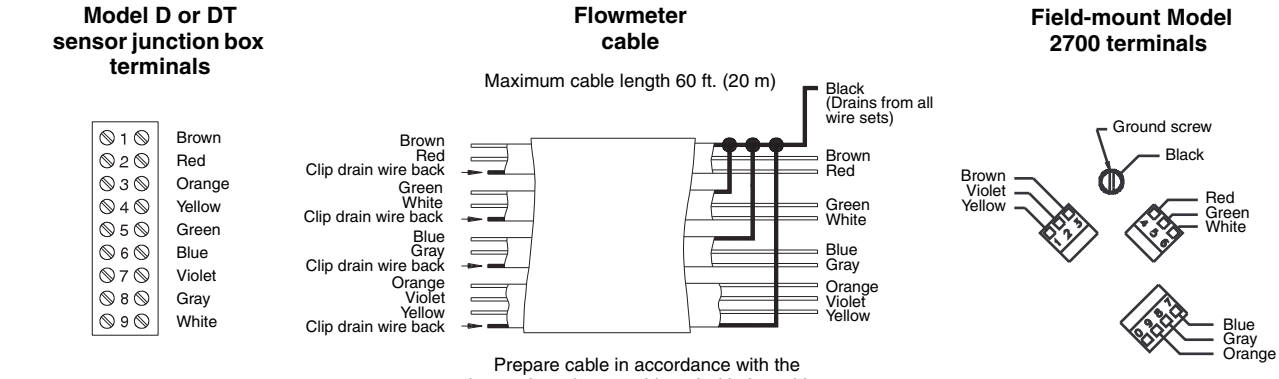
Model D or DT sensor (except D600) wiring to RFT9712 transmitter



For DT sensor junction box information, see page 20.

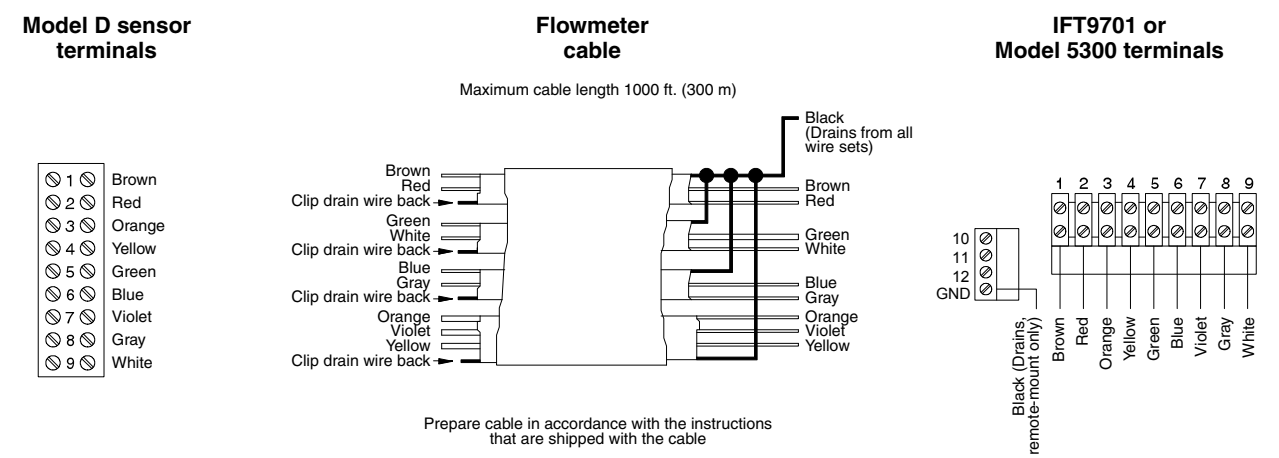
Prepare cable in accordance with the instructions that are shipped with the cable

Model D sensor or DT (except D600) wiring to Model 1700 or 2700 transmitter



Prepare cable in accordance with the instructions that are shipped with the cable. Do not allow shields to contact sensor junction box.

Model D sensor wiring (except the D600) to IFT9701* and Model 5300 transmitters



Prepare cable in accordance with the instructions that are shipped with the cable

** Model D600 and DT sensors cannot be used with IFT9701 transmitters*

D600 sensor

For wiring between the sensor and transmitter, there are two options: junction box or core processor.
- For wiring instructions from junction box to transmitter, see page 29.
- For wiring from core processor to transmitter or for direct host, see page 32.

The D600 also requires wiring to an AC power supply for the integral and remote version of the booster amplifier. Between 85-250 VAC of power must be provided. See pages 26-27.

The remote version of the booster amplifier requires wiring to the sensor and wiring of the drive wires. See page 28.

The sensor is shipped with 16 feet (5 meters) of 9-wire cable for connecting from the remote booster amplifier to the intrinsically safe junction box located on the sensor. For longer cable lengths, up to 60 feet (20 meters), contact Micro Motion.

⚠ CAUTION

Improper installation of wiring could cause measurement error or sensor failure.

- Shut off power before installing power-supply wiring.
- Follow all instructions to ensure sensor will operate correctly.
- Install drip legs in conduit or cable.
- Seal all conduit openings.
- Ensure integrity of gaskets, and fully tighten sensor junction-box cover, core processor cover, and all transmitter housing covers.

⚠ WARNING

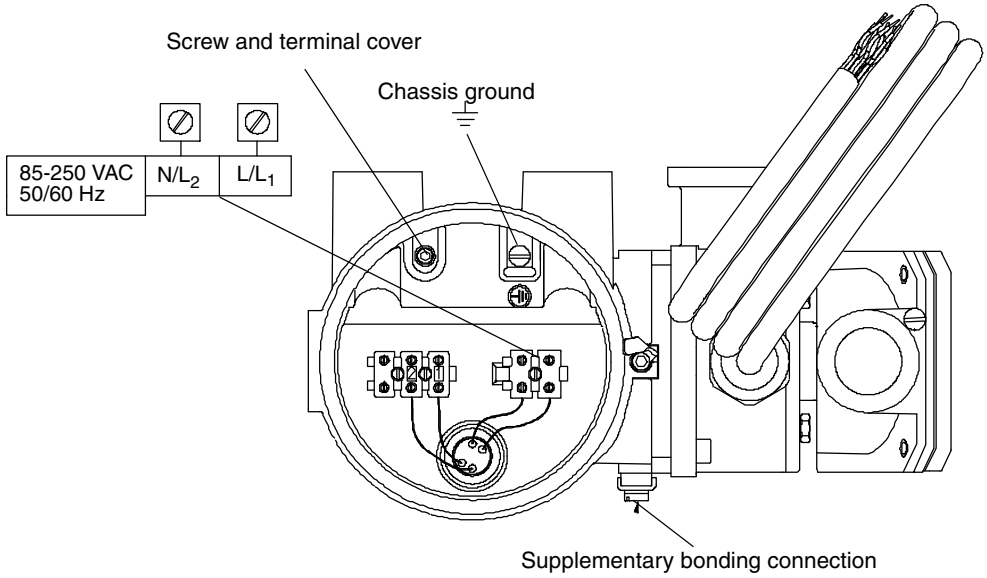
Explosion Hazard

In a hazardous area:
- Do not open booster amplifier housing cover while booster amplifier is energized.
- Wait at least 30 minutes after power is shut off before opening.

Power supply wiring to the remote booster amplifier

- Remove screw and terminal cover before installing wiring. Re-install cover before operating.
- Provide 85-250 VAC power to terminals L2 and L1 as shown in the diagram below.
- This unit is provided with an external terminal for supplementary bonding connections. This terminal is for use where local codes or authorities permit or require such connections.

Remote booster amplifier power-supply wiring

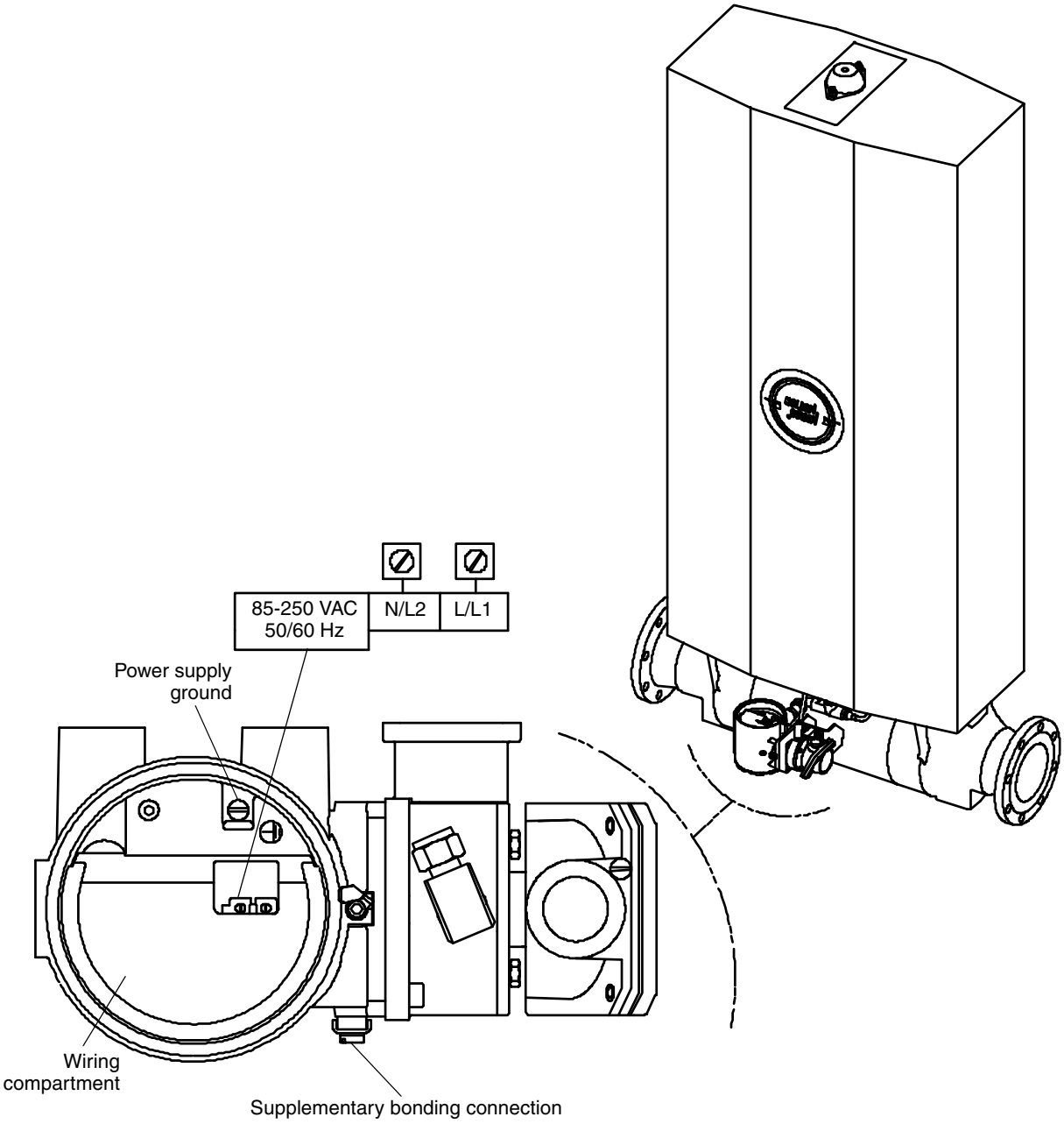


Power supply wiring to the integral booster amplifier

Provide 85-250 VAC power to terminals L2 and L1 as shown in the diagram below.

This unit is provided with an external terminal for supplementary bonding connections. This terminal is for use where local codes or authorities permit or require such connections.

Integral booster amplifier power-supply wiring



Wiring from the remote booster amplifier to the sensor

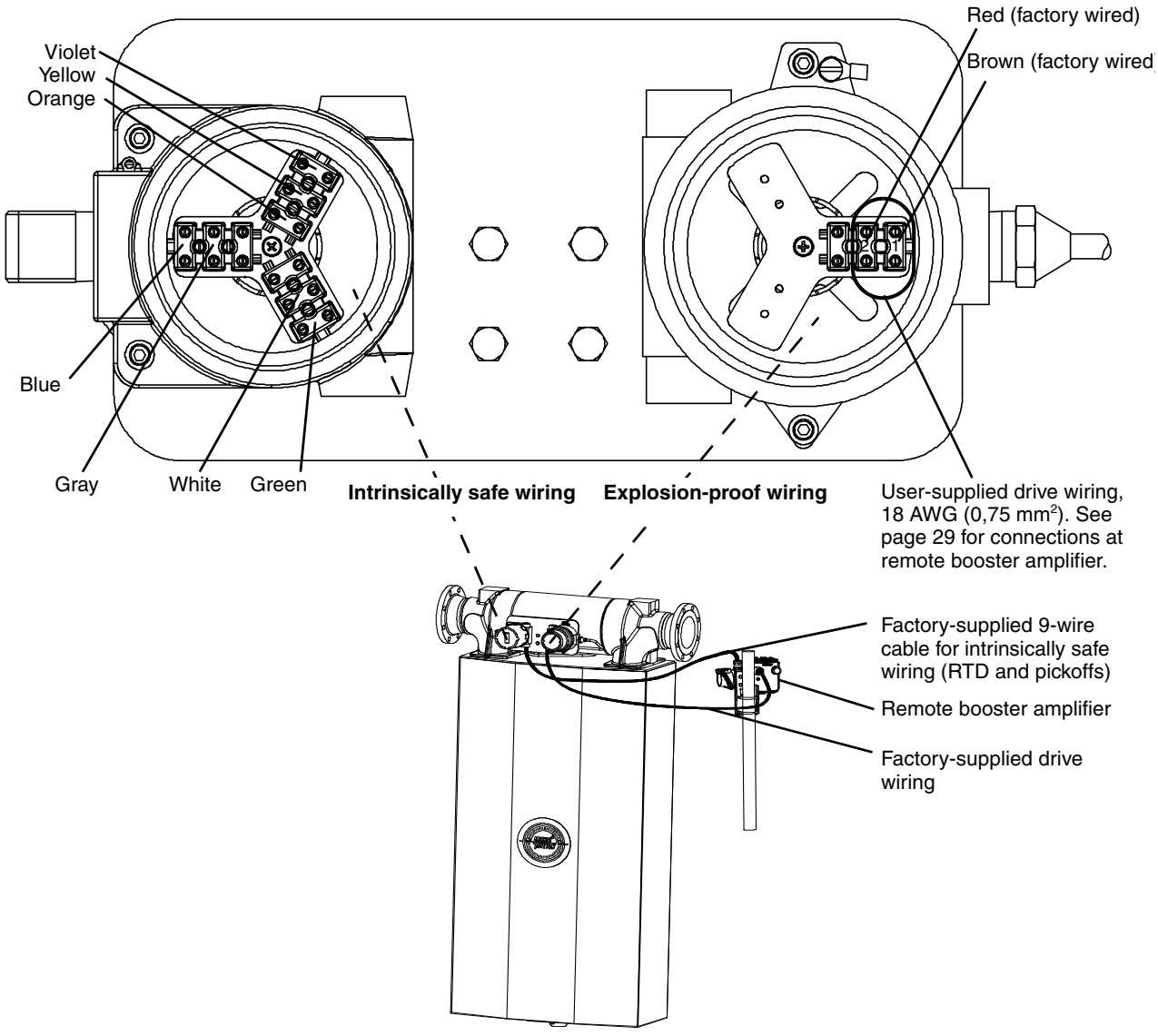
For intrinsically safe junction box wiring (see left side of figure below):

- Terminate factory-supplied 9-wire cable. Match wire colors to the corresponding terminal wire colors from the remote booster amplifier.
- Orange wire in cable does not have corresponding orange wire from sensor. Note: Terminate the orange wire in cable to the terminal shown in diagram below.
- Clip remaining wires (brown and red) of cable *(intrinsically safe side only)* and insulate.

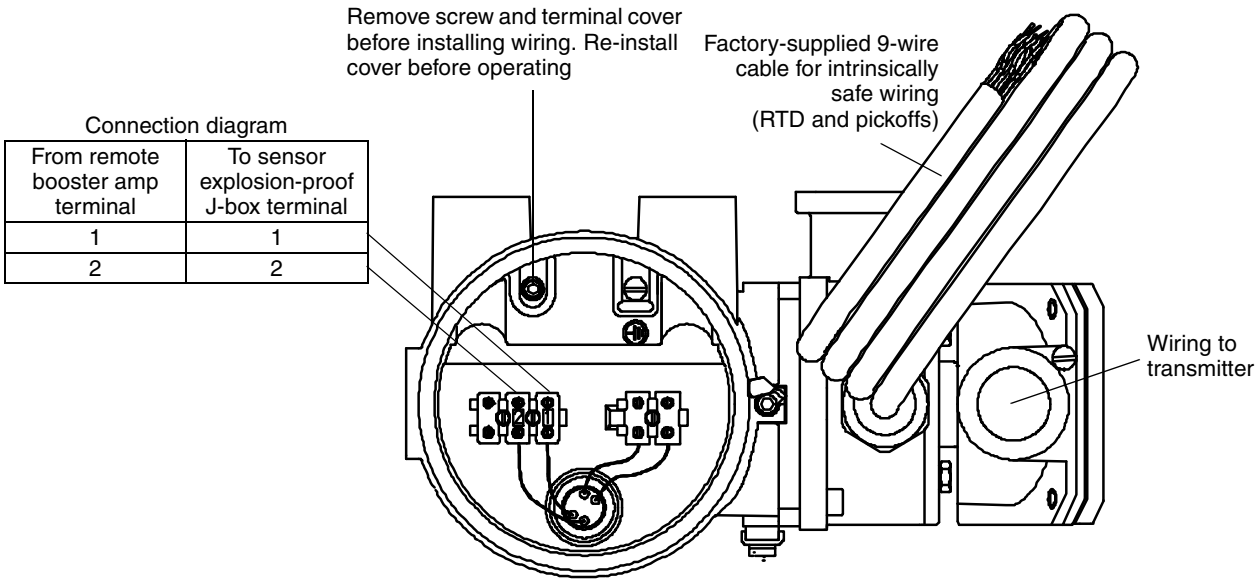
For explosion-proof junction box wiring (see right side of figure below):

Install user-supplied drive wiring, shielded 18 AWG (0,75 mm^2) 2-wire cable, from remote booster amplifier terminals 1 and 2 to sensor terminals 1 and 2. (See figure on page 29 for wiring at booster amplifier.)

Remote booster amplifier wiring to sensor



Remote booster amplifier drive wiring


Remove screw and terminal cover before installing wiring. Re-install cover before operating
Factory-supplied 9-wire cable for intrinsically safe wiring (RTD and pickoffs)
Wiring to transmitter

Connection diagram

From remote booster amp terminal	To sensor explosion-proof J-box terminal
1	1
2	2

Wiring to a transmitter (D600 sensor with junction box)

The instructions in this section explain how to connect a fully prepared 9-wire Micro Motion flowmeter cable to the sensor and transmitter.

- The procedure for preparing Micro Motion cable and cable glands is described in the instructions that are shipped with the cable.
- Install cable and wiring to meet local code requirements.

Cable connections to sensor and transmitter

The wiring procedure is the same for the sensor and transmitter. Refer to the wiring diagrams on the following pages, and follow these steps:

⚠ CAUTION

Failure to seal the sensor and transmitter housings could cause a short circuit, which would result in measurement error or flowmeter failure.

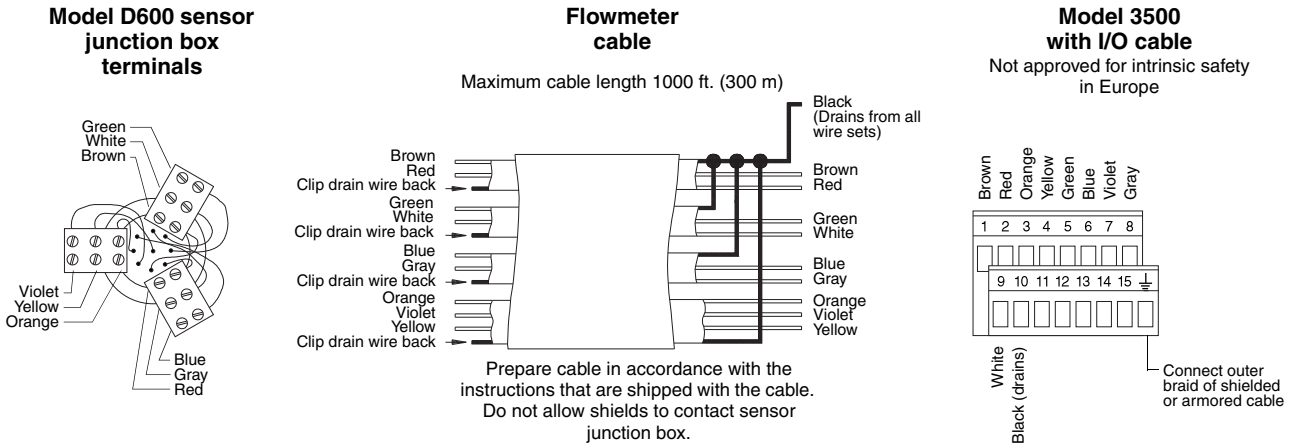
- Ensure integrity of gaskets and O-rings.
- Grease all O-rings before sealing.
- Install drip legs in cable or conduit.
- Seal all conduit openings.

1. Locate the wires by color and terminal number.
2. Insert the stripped ends of the individual wires into the terminal blocks. No bare wires should remain exposed.
   - At the sensor, connect wiring inside the junction box.
   - At the transmitter, connect wiring to the transmitter's intrinsically safe terminals for sensor wiring.
3. Tighten the screws to hold the wires in place.
4. Ensure integrity of gaskets, then tightly close and seal the junction-box cover and all housing covers on the transmitter.

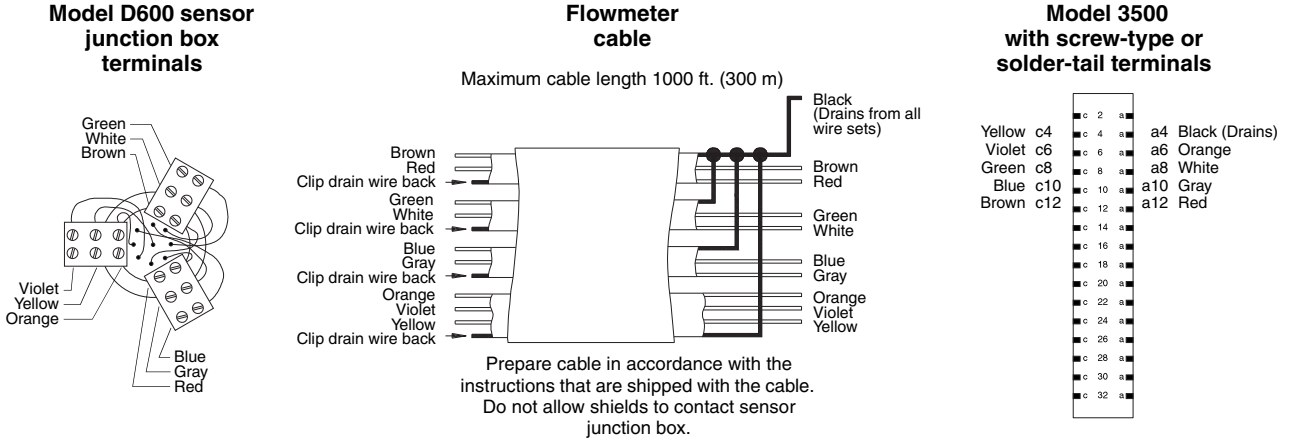
⚠ CAUTION

Drain wires from a 9-wire cable must be clipped at the sensor end and insulated with heat-shrink wrapping. Failure to properly terminate drain wires will cause sensor error.

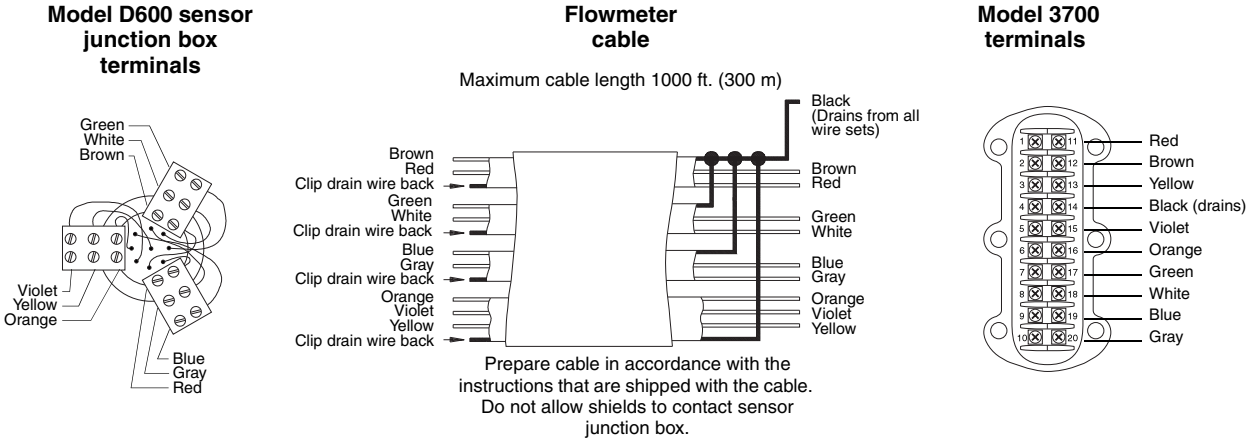
Model D600 wiring to Model 3500 with I/O cable



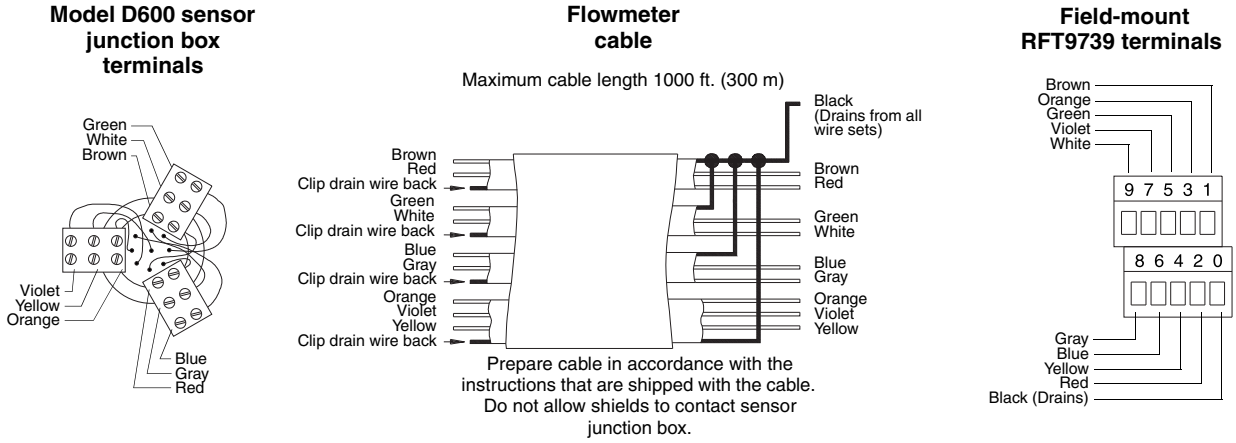
Model D600 wiring to Model 3500 with screw or solder terminals



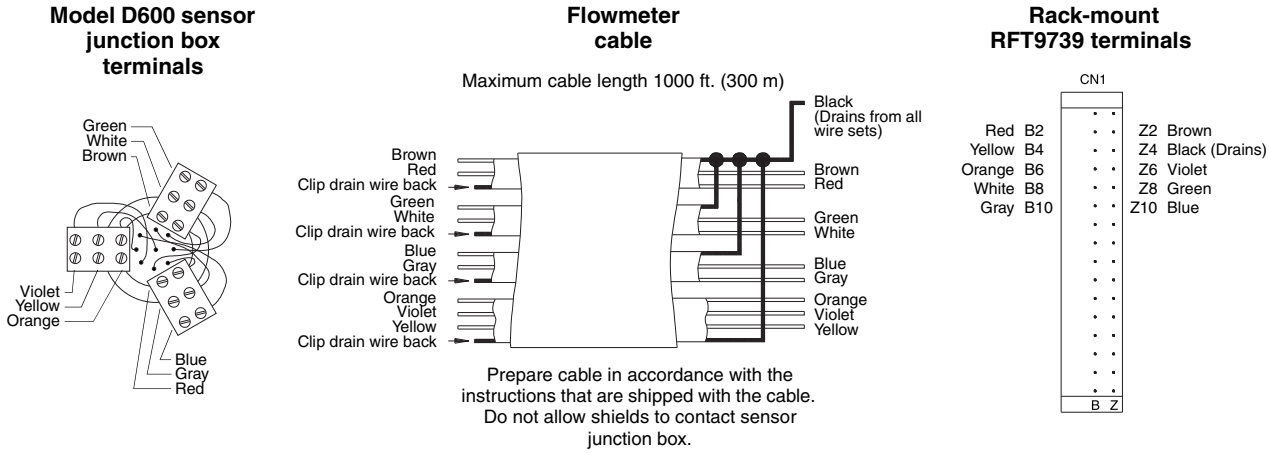
Model D600 wiring to Model 3700



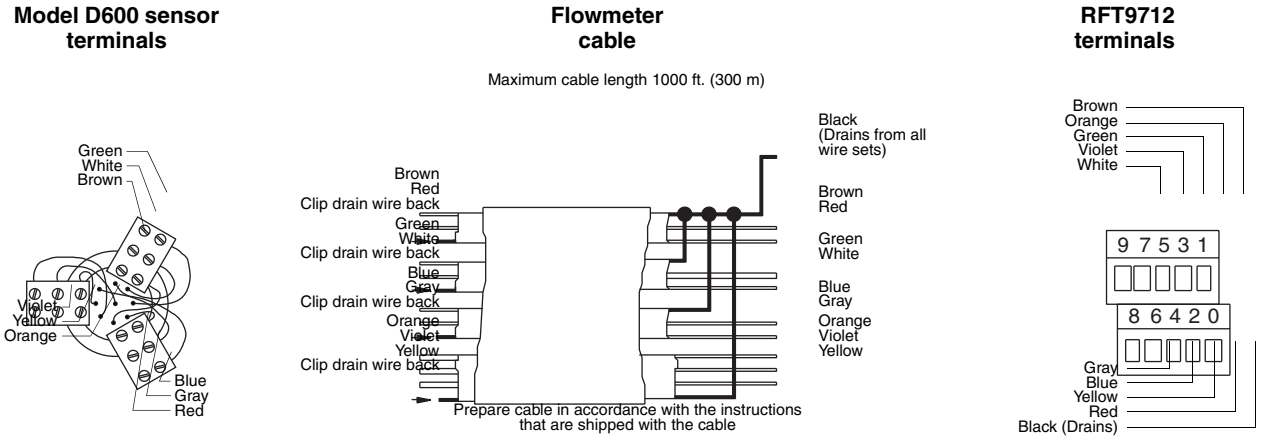
Model D600 wiring to RFT9739 field-mount transmitter



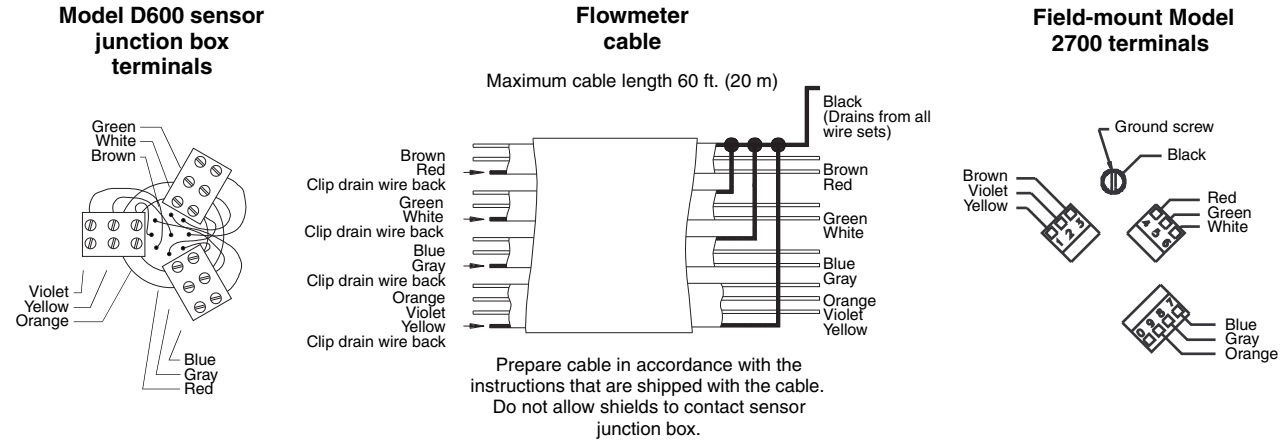
Model D600 wiring to RFT9739 rack-mount transmitter



Model D600 wiring to RFT9712 transmitter



Model D600 sensor wiring to the 9-wire Model 1700 or 2700 transmitter



Core processor to a 4-wire remote transmitter or remote host

To connect wiring at the core processor:

1. Use one of the following methods to shield the wiring from the core processor to the remote transmitter:

   - If you are installing unshielded wiring in continuous metallic conduit that provides 360° termination shielding for the enclosed wiring, go to Step 6, page 35.

   - If you are installing user-supplied cable gland with shielded cable or armored cable, terminate the shields in the cable gland. Terminate both the armored braid and the shield drain wires in the cable gland.

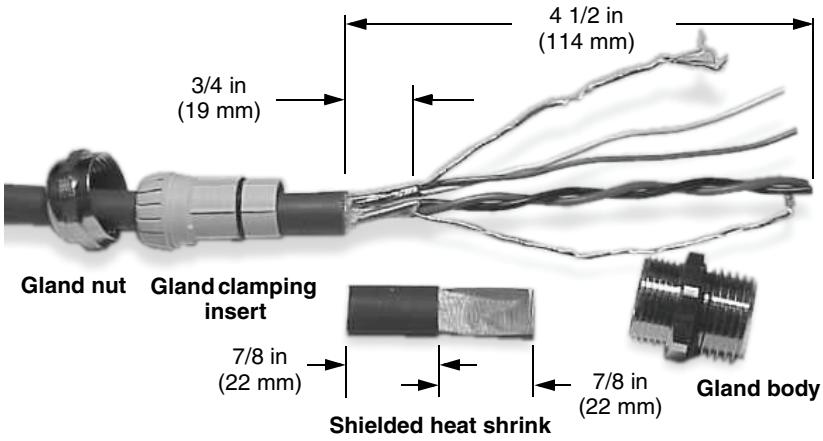
   - If you are installing a Micro Motion-supplied cable gland at the core processor housing:

     - Prepare the cable and apply shielded heat shrink as described below. The shielded heat shrink provides a shield termination suitable for use in the gland when using cable whose shield consists of foil and not a braid. Proceed to Step 2.

- With armored cable, where the shield consists of braid, prepare the cable as described below, but do not apply heat shrink. Proceed to Step 2.

2. Remove the cover from the core processor.

3. Slide the gland nut and the clamping insert over the cable.



4. For connection at the core processor housing, prepare shielded cable as follows (for armored cable, omit steps d, e, f, and g):

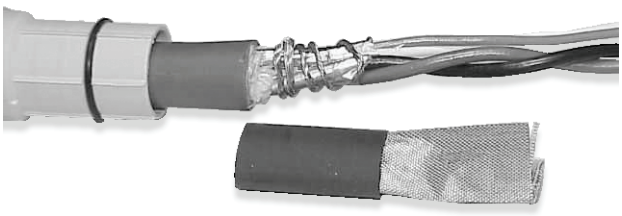
   a. Strip 4 1/2 inches (114 mm) of cable jacket.

   b. Remove the clear wrap that is inside the cable jacket, and remove the filler material between the wires.

   c. Remove the foil shield that is around the insulated wires, leaving 3/4 inch (19 mm) of foil or braid and drain wires exposed, and separate the wires.

   d. Wrap the shield drain wire(s) around the exposed foil twice. Cut off the excess wire.

Shield drain wire(s) wrapped twice around exposed shield foil



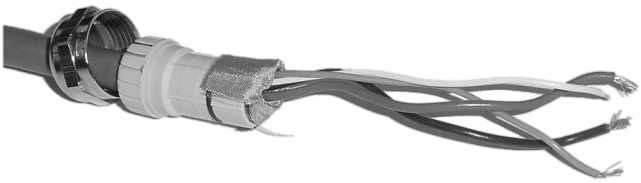
   e. Place the EMI-shielded heat shrink over the exposed shield drain wire(s). The tubing should completely cover the drain wires.

   f. Without burning the cable, apply heat (250 °F or 120 °C) to shrink the tubing.

Shielded heat shrink completely covers exposed drain wires

g. Position gland clamping insert so the interior end is flush with the heat shrink.

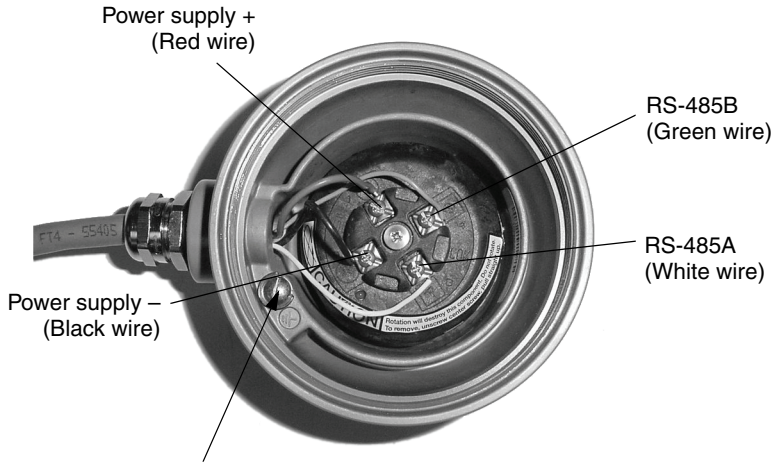
h. Fold the cloth shield or braid and drain wires over the clamping insert and approximately 1/8 inch (3 mm) past the O-ring.



i. Install the gland body into the core processor housing conduit opening.

5. Insert the wires through the gland body and assemble the gland by tightening the gland nut.

6. Identify the wires in the 4-wire cable. The 4-wire cable supplied by Micro Motion consists of one pair of 18 AWG (0,75 mm^2) wires (red and black), which should be used for the VDC connection, and one pair of 22 AWG (0,35 mm^2) wire (green and white), which should be used for the RS-485 connection. Connect the four wires to the numbered slots on the core processor, matching corresponding numbered terminals on the transmitter.



Core processor housing internal ground screw
- For connections to earth ground when sensor cannot be grounded via piping and local codes require ground connections to be made internally
- Do not connect shield drain wires to this terminal

7. Reattach the core processor housing.

⚠ WARNING

Twisting the core processor will damage the sensor.

Do not twist the core processor.

8. Shield and shield drain wire(s) should not be grounded at the transmitter.

   - For wiring at the transmitter, see the transmitter Quick Reference Guide (QRG).

   - If you are connecting to an MVDSolo with MVD Direct Connect™ I.S. barrier supplied by Micro Motion, the barrier supplies power to the core processor. Refer to the barrier documentation to identify the terminals at the barrier.

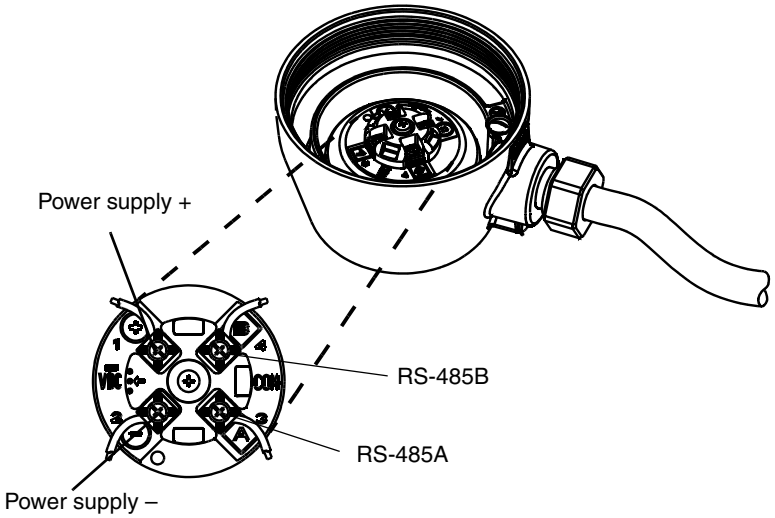
   - If you are connecting to an MVDSolo without I.S. barrier:

     - Connect the VDC wires from the core processor (see figure on page 36) to an independent power supply. This power supply must connect only to the core processor. A recommended power supply is the SDN series of 24-VDC power supplies manufactured by Sola/Hevi-Duty.

     - Do not ground either connection of the power supply.

     - Connect the RS-485 wires from the core processor (see figure below) to the RS-485 terminals at the remote host. Refer to the vendor documentation to identify the terminals.

Core processor terminals



Sensor grounding

Ground the sensor and transmitter independently.

⚠ CAUTION

Improper grounding could cause measurement error.

To reduce the risk of measurement error:
- Ground the flowmeter to earth, or follow ground network requirements for the facility.
- For installation in an area that requires intrinsic safety, refer to Micro Motion hazardous approval documentation, shipped with the sensor or available from the Micro Motion web site.
- For hazardous area installations in Europe, refer to standard EN 60079-14 if national standards do not apply.

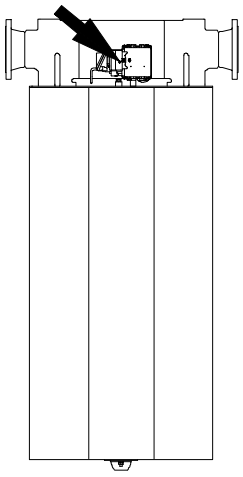
The sensor can be grounded via the piping if the joints in the pipeline are ground-bonded. If the sensor is not grounded via the piping, connect a ground wire to the internal or external grounding screw, which is located on the core processor or junction box.

If national standards are not in effect, follow these guidelines:
- Use copper wire, 14 AWG (2,5 mm^2) or larger wire size for grounding.
- Keep all ground leads as short as possible, less than 1 ohm impedance.
- Connect ground leads directly to earth, or follow plant standards.

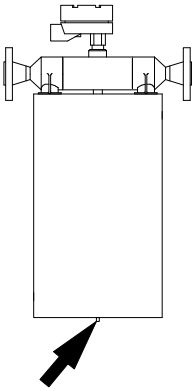
Refer to the transmitter documentation for instructions on grounding the transmitter.

Sensor grounding screw

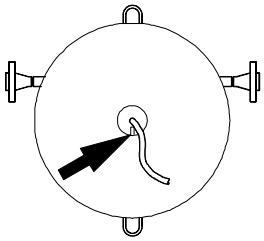
Model D600 sensors



Other Model D sensors



Model DT sensors



Startup

Zeroing

After the flowmeter has been fully installed, you must perform the zeroing procedure. Flowmeter zeroing establishes flowmeter response to zero flow and sets a baseline for flow measurement. Refer to the transmitter instruction manual for information on performing the zeroing procedure.

Configuration, calibration, and characterization

You can use the transmitter to configure, calibrate, and characterize the meter. For more information, refer to the transmitter instruction manuals.

The following information explains the difference between configuration, calibration, and characterization. Certain parameters might require *configuration* even when *calibration* is not necessary.

Configuration parameters include such items as flowmeter tag, measurement units, flow direction, damping values, and slug flow parameters. If requested at time of order, the meter is configured at the factory according to customer specifications.

Calibration accounts for the flowmeter's sensitivity to flow, density, and temperature. Calibration is done at the factory.

Characterization is the process of entering calibration factors for flow, density, and temperature directly into transmitter memory, instead of performing field calibration procedures. Calibration factors can be found on the sensor serial number tag and on the certificate that is shipped with the sensor.

For instructions about flowmeter configuration, calibration, and characterization, see the manual that was shipped with the transmitter.

If the sensor and transmitter are ordered together as a Coriolis flowmeter, the factory has characterized the meter — no additional characterization is necessary. If either the sensor or transmitter is replaced, characterization is required.

Customer Service

The Micro Motion Customer Service Department is available for assistance with flowmeter startup if you experience problems you cannot solve on your own.

If possible, provide us with the model numbers and/or serial numbers of your Micro Motion equipment, which will assist us in answering your questions.

- In the U.S.A., phone **1-800-522-MASS** (1-800-522-6277), 24 hours
- In Canada and Latin America, phone +1 303-527-5200 (U.S.A.)
- In Asia, phone +65 6777-8211 (Singapore)
- In the U.K., phone 0870 240 1978 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 555 (The Netherlands)
- Or visit our website at **www.micromotion.com**.

Troubleshooting

General information

Most troubleshooting is performed at the transmitter. However, the following troubleshooting topics are described in this manual:

- *Zero drift*, page 42
- *Erratic flow rate*, page 43
- *Inaccurate flow rate or batch total*, page 44
- *Inaccurate density reading*, page 45
- *Inaccurate temperature reading*, page 46

If you cannot find the problem you are looking for, check the transmitter instruction manual.

To troubleshoot the flowmeter, you might need a digital multimeter (DMM) or similar device, the transmitter display, if it has one, and one of the following:

- HART Communicator
- ProLink or ProLink II software
- AMS software
- Modbus master controller (RFT9739, Series 1000, or Series 2000)
- Fieldbus host controller (Series 1000 or Series 2000)
- Profibus-PA host controller (Series 1000 or Series 2000)

If you cannot find the problem you are looking for, or if troubleshooting fails to reveal the problem, contact the Micro Motion Customer Service Department.

If possible, provide us with the model numbers and/or serial numbers of your Micro Motion equipment, which will assist us in answering your questions.

- In the U.S.A., phone **1-800-522-MASS** (1-800-522-6277), 24 hours
- In Canada and Latin America, phone +1 303-527-5200 (U.S.A.)
- In Asia, phone +65 6777-8211 (Singapore)
- In the U.K., phone 0870 240 1978 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 555 (The Netherlands)

Zero drift

Symptom

The flowmeter indicates the process fluid is flowing while flow is stopped; or indicates a flow rate that does not agree with a reference rate at low flow, but does agree at higher flow rates.

Troubleshooting instructions

To troubleshoot zero drift, you will need one of the communications devices listed on page 46 or a transmitter with a display. Refer to the table below for the necessary steps to troubleshoot zero drift.

Table 1. Troubleshooting zero drift

Procedure	Instructions	What to do next
1. Check for leaking valves and seals		• If no leaks are found, go to step 2 • If leaks are found, eliminate them, then go to step 15
2. Check the flow units	See page 46	• If the flow units are OK, go to step 3 • If the flow units are wrong, change them, then go to step 15
3. Make sure the flowmeter was zeroed properly	See page 39	• If the flowmeter was zeroed properly, go to step 4 • If the flowmeter was not zeroed properly, zero it, then go to step 15
4. Check for the proper flow calibration factor	See page 49	• If the flow cal factor is correct, go to step 5 • If the flow cal factor is incorrect, change it, then go to step 15
5. Check the damping value	See page 50	• If the damping value is OK, go to step 6 • If the damping value is too low, change it, then go to step 15
6. Check for two-phase flow	See page 53	• If there is no two-phase flow, go to step 7 • If there is two-phase flow, fix the problem, then go to step 15
7. Check for moisture in the sensor junction box	See page 52	• If there is no moisture present, go to step 8 • If there is moisture in the junction box, dry out and seal the junction box, then go to step 15
8. Check for faulty or improperly installed flowmeter wiring	See page 47	• If the wiring is OK, go to step 9 • If the wiring is faulty, fix or replace it, then go to step 15
9. Check for faulty or improperly installed grounding	See page 51	• If the grounding is OK, go to step 10 • If the grounding is incorrect or faulty, fix it, then go to step 15
10. Check for mounting stress on the sensor	See page 53	• If the sensor mount is OK, go to step 11 • If there are mounting stresses, fix it, then go to step 15
11. Check for vibration or crosstalk	See page 53	• If there is no vibration or crosstalk, go to step 12 • If there is vibration or crosstalk, eliminate it, then go to step 15
12. Make sure the sensor is oriented properly	See page 13	• If the sensor is oriented properly, go to step 13 • If the sensor is not oriented properly, change the orientation, then go to step 15
13. Check for plugging or build-up on the sensor flow tubes	See page 54	• If the tubes are not plugged, go to step 14 • If there is plugging or build-up, clear the tubes, then go to step 15
14. Check for RF interference	See page 51	• If there is no interference, or the source cannot be detected, go to step 16 • If there is interference, eliminate it, then go to step 15
15. Check again for zero drift		• If there is no longer any zero drift, you've solved the problem • If the zero drifts again, start over at step 3 or go to step 16
16. Contact Micro Motion	Phone numbers are listed on page 41	

Erratic flow rate

Symptom

The flowmeter indicates the flow rate is varying, even though it is steady.

Troubleshooting instructions

To troubleshoot an erratic flow rate, you will need one of the communications devices listed on page 46 or a transmitter with a display. Refer to the table below for the necessary steps to troubleshoot an erratic flow rate.

Table 2. Troubleshooting erratic flow rate

Procedure	Instructions	What to do next
1. Check for erratic flow rate at the transmitter	See page 47	• If the signal is stable at the transmitter, go to step 2 • If the signal is erratic at the transmitter, go to step 4
2. Check for faulty output wiring	See page 47	• If the output wiring is OK, go to step 3 • If the output wiring is faulty, repair or replace it, then go to step 13
3. Check the receiving device for malfunctions	See instruction manual for the device	• If the receiving device is OK, go to step 4 • If the receiving device is faulty, contact the manufacturer
4. Check the flow units	See page 46	• If the flow units are OK, go to step 5 • If the flow units are wrong, change them, then go to step 13
5. Check the damping value	See page 50	• If the damping value is OK, go to step 6 • If the damping value is too low, change it, then go to step 13
6. Check for stable drive gain	See page 50	• If the drive gain is stable, go to step 7 • If the drive gain is not stable, go to step 11
7. Check for a stable density reading	See page 50	• If the density reading is stable, go to step 8 • If the density reading is not stable, go to step 11
8. Check for faulty or improperly installed flowmeter wiring	See page 47	• If the flowmeter wiring is OK, go to step 9 • If the flowmeter wiring is incorrect or faulty, fix or replace it, then go to step 13
9. Check for faulty or improperly installed grounding	See page 51	• If the grounding is OK, go to step 10 • If the grounding is incorrect or faulty, fix it, then go to step 13
10. Check for vibration or crosstalk	See page 53	• If there is no vibration or crosstalk, go to step 11 • If there is vibration or crosstalk, eliminate it, then go to step 13
11. Check for two-phase flow	See page 53	• If there is no two-phase flow, go to step 12 • If there is two-phase flow, fix the problem, then go to step 13
12. Check for plugging or build-up on the sensor flow tubes	See page 54	• If the tubes are not plugged, go to step 14 • If there is plugging or build-up, clear the tubes, then go to step 13
13. Check again for erratic flow rate	See page 47	• If the signal is no longer erratic, you've solved the problem • If the signal is still erratic, start over at step 1 or go to step 14
14. Contact Micro Motion	Phone numbers are listed on page 41	

Inaccurate flow rate or batch total

Symptom

The flowmeter indicates a flow rate or batch total that does not agree with a reference rate or total.

Troubleshooting instructions

To troubleshoot an inaccurate flow rate or batch total, you will need one of the communications devices listed on page 46 or a transmitter with a display. Refer to the table below for the necessary steps to troubleshoot an inaccurate rate or total.

Table 3. Troubleshooting inaccurate flow rate or batch total

Procedure	Instructions	What to do next
1. Check for the proper flow calibration factor	See page 49	• If the flow cal factor is correct, go to step 2 • If the flow cal factor is incorrect, change it, then go to step 15
2. Check the flow units	See page 46	• If the flow units are OK, go to step 3 • If the flow units are wrong, change them, then go to step 15
3. Make sure the flowmeter was zeroed properly	See page 39	• If the flowmeter was zeroed properly, go to step 4 • If the flowmeter was not zeroed properly, zero it, then go to step 15
4. Is the flow measurement configured for mass or volume?	See page 46	• If the configuration is for mass, go to step 6 • If the configuration is for volume, go to step 5
5. Check for the proper density calibration factor	See page 49	• If the dens cal factor is correct, go to step 6 • If the dens cal factor is incorrect, change it, then go to step 15
6. Make sure the density reading is accurate for the fluid	See page 50	• If the density reading is correct, go to step 7 • If the density reading is wrong, go to step 11
7. Make sure the temperature reading is accurate for the fluid	See page 50	• If the temperature reading is correct, go to step 8 • If the temperature reading is wrong, go to step 14
8. Is the flow measurement configured for mass or volume?	See page 46	• If the configuration is for mass, go to step 11 • If the configuration is for volume, go to step 9
9. Is the reference total based on a fixed density value?		• If the total is based on a fixed value, go to step 10 • If the total is not based on a fixed value, go to step 11
10. Change flow units to mass flow units	See page 46	• Go to step 15
11. Check for faulty or improperly installed grounding	See page 51	• If the grounding is OK, go to step 12 • If the grounding is incorrect or faulty, fix it, then go to step 15
12. Check for two-phase flow	See page 53	• If there is no two-phase flow, go to step 13 • If there is two-phase flow, fix the problem, then go to step 15
13. Check the scale (or reference measurement) for accuracy	Use your plant procedures	• If the scale is accurate, go to step 14 • If the scale is not accurate, fix it, then go to step 15
14. Check for faulty or improperly installed flowmeter wiring	See page 47	• If the flowmeter wiring is OK, go to step 16 • If the flowmeter wiring is incorrect or faulty, fix or replace it, then go to step 15
15. Run a new batch and check again for an inaccurate rate or total		• If the rate or total is correct, you've solved the problem • If the rate or total is wrong, start over at step 2 or go to step 16
16. Contact Micro Motion	Phone numbers are listed on page 41	

Inaccurate density reading

Symptom

The flowmeter density measurement is erratic, or is lower or higher than the density of the fluid.

Troubleshooting instructions

To troubleshoot an inaccurate density reading, you will need one of the communications devices listed on page 46 or a transmitter with a display. Refer to the table below for the necessary steps to troubleshoot an inaccurate density reading.

Table 4. Troubleshooting inaccurate density reading

Procedure	Instructions	What to do next
1. Check for stable density reading at the transmitter	See page 50	• If the density reading is stable, go to step 2 • If the density reading is not stable, go to step 3
2. Check for the proper density calibration factor	See page 49	• If the dens cal factor is correct, go to step 4 • If the dens cal factor is incorrect, change it, then go to step 11
3. Check for faulty or improperly installed flowmeter wiring	See page 47	• If the flowmeter wiring is OK, go to step 4 • If the flowmeter wiring is incorrect or faulty, fix or replace it, then go to step 11
4. Check for faulty or improperly installed grounding	See page 51	• If the grounding is OK, go to step 5 • If the grounding is incorrect or faulty, fix it, then go to step 11
5. Check to see if the density reading is low or high	See page 50	• If the density reading is low, go to step 6 • If the density reading is high, go to step 10
6. Run a quality check on the process fluid	Use your plant procedures	• If the product quality is OK, go to step 7 • If the product quality is not OK, fix it, then go to step 11
7. If you checked the wiring in step 3, go to step 8, otherwise, check for faulty or improperly installed flowmeter wiring	See page 47	• If the flowmeter wiring is OK, go to step 8 • If the flowmeter wiring is incorrect or faulty, fix or replace it, then go to step 11
8. Check for two-phase flow	See page 53	• If there is no two-phase flow, go to step 9 • If there is two-phase flow, fix the problem, then go to step 11
9. Check for vibration or crosstalk	See page 53	• If there is no vibration or crosstalk, go to step 12 • If there is vibration or crosstalk, eliminate it, then go to step 11
10. Check for plugging or build-up on the sensor flow tubes	See page 54	• If the tubes are not plugged, go to step 12 • If there is plugging or build-up, clear the tubes, then go to step 11
11. Check again for inaccurate density reading at the transmitter	See page 50	• If the reading is correct, you've solved the problem • If the reading is still wrong, start over at step 1 or go to step 12
12. Contact Micro Motion	Phone numbers are listed on page 41	

Inaccurate temperature reading

Symptom
The flowmeter temperature reading is different than expected.

Troubleshooting instructions
To troubleshoot an inaccurate temperature reading, you will need one of the communications devices listed on page 46 or a transmitter with a display. Refer to the table below for the necessary steps to troubleshoot an inaccurate temperature reading.

Table 5. Troubleshooting inaccurate temperature reading

Procedure	Instructions	What to do next
1. Check for faulty or improperly installed flowmeter wiring	See page 47	• If the flowmeter wiring is OK, go to step 2 • If the flowmeter wiring is faulty, fix or replace it, then go to step 3
2. Check for the proper temperature calibration factor	See page 49	• If the temp cal factor is correct, go to step 4 • If the temp cal factor is incorrect, change it, then go to step 3
3. Check again for inaccurate temperature reading at the transmitter	See page 50	• If the reading is correct, you've solved the problem • If the reading is still wrong, start over at step 1 or go to step 4
4. Contact Micro Motion	Phone numbers are listed on page 41	

Troubleshooting at the transmitter

The tables in the preceding sections refer you to this section for instructions on troubleshooting at the transmitter. To troubleshoot at the transmitter, you might need a digital multimeter (DMM) or similar device, the transmitter display, if it has one, and one of the following:

- HART Communicator
- ProLink or ProLink II software
- AMS software
- Modbus master controller (RFT9739 only, Series 1000, or Series 2000)
- Fieldbus host controller (Series 1000, or Series 2000)
- Profibus host controller (Series 1000 or 2000)

Checking or changing the flow units
Check or change the flow units (units of measure) configuration at the transmitter. If necessary, refer to the instruction manual (or on-line help for software) for the method you choose.

- Use the transmitter display, if it has one
- Use a HART Communicator, ProLink software, or AMS software
- Use a Modbus, fieldbus, or Profibus-PA host controller

Make sure the configured units of measure are the ones you want. Also, make sure you know what the abbreviations mean. For example, g/sec is grams per second, not gallons per second.

Checking for erratic flow rate at the transmitter
Before troubleshooting erratic flow rate, you must first determine whether it is a result of the transmitter or a connected output device. Check for an erratic flow signal at the transmitter using any of the following methods. If necessary, refer to the instruction manual (or on-line help for software) for the method you choose.
- Use the transmitter display, if it has one
- Use a HART Communicator, ProLink software, or AMS software
- Use a Modbus, fieldbus, or Profibus-PA host controller
- Use a DMM on the transmitter's 4-20 mA or frequency output terminals

If the flow rate or output signal is not erratic at the transmitter outputs, the problem is not with the transmitter.

Checking for faulty output wiring
Having already checked the output at the transmitter end (above), use a DMM to check the signal at the other end (the receiving end) of the output wiring. If the signal is not erratic, the problem is not with the output wiring.

Checking for faulty flowmeter wiring
Wiring problems are often incorrectly diagnosed as a faulty sensor. Examine wiring between the sensor and transmitter as follows:

1. ***Check the cable preparation.*** The flowmeter cable must be prepared correctly. The most common problem is improperly prepared drain wires. See illustration, below. The drains are clipped at the sensor end. They should not be connected to any terminals in the sensor junction box. See wiring diagrams, pages 22-32.

2. ***Check wire terminations.*** Check to be sure wires are secured tightly in the terminal blocks, and making good connections. Make sure no wires remain exposed at either end of the flowmeter cable.

3. ***Check ohm levels.*** If the cable was properly prepared and terminal connections are good, check resistance across wire pairs to determine whether the flowmeter cable is faulty. The procedure is performed first at the transmitter, then at the sensor. Follow these steps:
   a. Disconnect the transmitter's power supply.
   b. Disconnect sensor wiring from the transmitter's flowmeter terminals.

c. Use a DMM to measure resistance across wire pairs at the transmitter end of the cable. See table on page 48.
   - If the measured value is within the range listed in the table, reconnect wiring and restore power to the transmitter.
   - If the measured resistance is outside the range listed in the table, repeat the measurements at the sensor junction box.
     - If the sensor is a *not* a D600, refer to the "Nominal resistance ranges" table below.
     - If the sensor is a D600, refer to the table and illustration on page 49.
     - If resistance values measured at the sensor are also outside the range listed in the table, the sensor might be faulty.

Cross-section of cable with drain wires

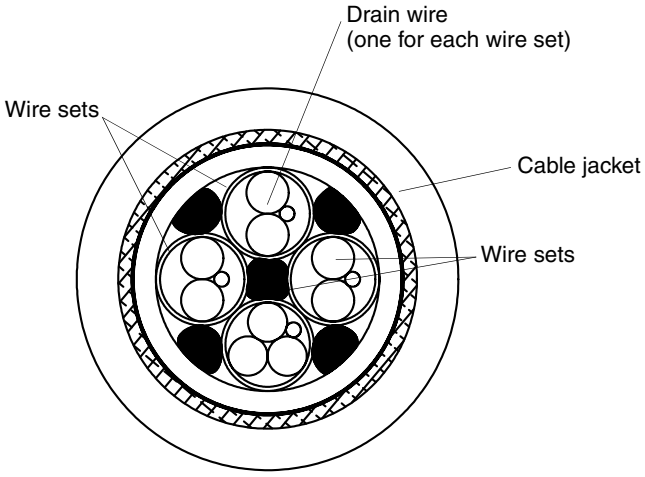


Table 6. Nominal resistance ranges for flowmeter circuits (for all D and DT sensors except the D600)

Notes

- Disconnect wires from terminals before checking resistance values.
- Temperature-sensor value increases 0.38675 ohms per °C increase in temperature.
- Nominal resistance values will vary 40% per 100°C. However, confirming an open coil or shorted coil is more important than any slight deviation from the resistance values presented below.
- Resistance across blue and gray wires (right pickoff circuit) should be within 10% of resistance across green and white wires (left pickoff circuit).
- Actual resistance values depend on the sensor model and date of manufacture.
- Reading across wire pairs should be steady.

Circuit	Wire colors	Sensor terminals*	Nominal resistance range
Drive coil	Brown to red	1 to 2	8 to 2650 Ω
Left pickoff	Green to white	5 to 9	16 to 300 Ω
Right pickoff	Blue to gray	6 to 8	16 to 300 Ω
Temperature sensor	Orange to violet	3 to 7	100 Ω at 0°C + 0.38675 Ω / °C
Lead length compensator	Yellow to violet	4 to 7	100 Ω at 0°C + 0.38675 Ω / °C

* For transmitter terminal designations, refer to the table below. For D600 sensors, see the illustration and table on page 49.

Checking ohm levels at a D600 sensor (applicable only to sensors with a junction box)

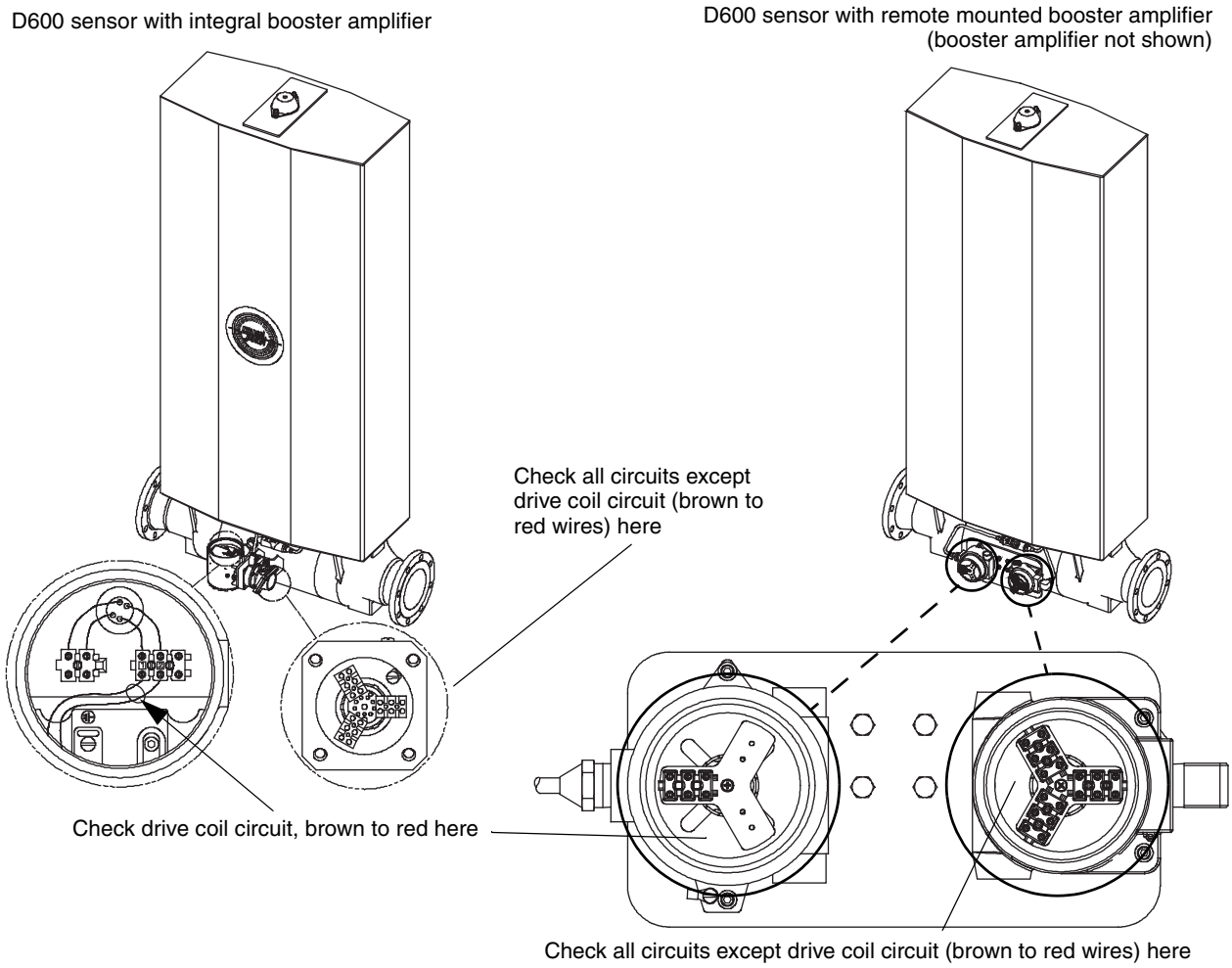

D600 sensor with integral booster amplifier
D600 sensor with remote mounted booster amplifier (booster amplifier not shown)
Check all circuits except drive coil circuit (brown to red wires) here
Check drive coil circuit, brown to red here
Check all circuits except drive coil circuit (brown to red wires) here

Table 7. Nominal resistance values for D600 circuits

Notes

- Disconnect wires from terminals before checking resistance values.
- Temperature-sensor value increases 0.38675 ohms per °C increase in temperature.
- Nominal resistance values will vary 40% per 100 °C. However, confirming an open coil or shorted coil is more important than any slight deviation from the resistance values presented below.
- Resistance across blue and gray wires (right pickoff circuit) should be within 10% of resistance across green and white wires (left pickoff circuit).
- Actual resistance values depend on the sensor model and date of manufacture.
- Reading across wire pairs should be steady.
- See previous illustration for terminal locations.

Circuit	Wire colors	Approximate nominal resistance
Drive coil	Brown to red	16 Ω
Primary left pickoff	Green to white	140 Ω
Primary right pickoff	Blue to gray	140 Ω
Secondary left pickoff	Brown to white	140 Ω
Secondary right pickoff	Red to gray	140 Ω
Temperature sensor	Yellow to violet	100 Ω at 0 °C + 0.38675 Ω / °C

Checking the calibration factors
Check or change the flow, density, or temperature calibration factors at the transmitter. The temperature cal factor is for the RFT9739, Model 1700, Model 2700, Model 3500, and 3700 only. If necessary, refer to the instruction manual (or on-line help for software) for the method you choose.

- Use the Model 3500 or 3700 display
- Use a HART Communicator, ProLink or ProLink II software, or AMS software
- Use the host controller

Enter the calibration factors that are listed on the flowmeter calibration tag. (Calibration factors are also listed on the certificate that was shipped with the meter.) If the calibration factors at the flowmeter are already correct, the problem is not with the calibration factors.

Checking the damping value
Check or change the damping value at the transmitter. If necessary, refer to the instruction manual (or on-line help for software) for the method you choose.
- Use the Model 3500 or 3700 display
- Use a HART Communicator, ProLink software, or AMS software
- Use the host controller

In almost all applications, the damping value should be greater than or equal to 0.8 seconds. If the damping value is already greater than or equal to 0.8 seconds, the problem is probably not with the damping value.

Damping values less than 0.8 seconds are used in very few applications. After troubleshooting is complete, if you have a question about whether your application might require a lower damping value, contact the Micro Motion Customer Service Department. Phone numbers are listed on page 41. The two most common applications affected by a damping value that is too high are:
- Very short batching applications
- Very short-pass proving applications

Checking the drive gain
Contact Micro Motion to check the drive gain. Phone numbers are listed on page 41.

If the transmitter is a Model 1700, 2700, 3500, or 3700, you can use the display to view drive gain. For more information, refer to the manual that is shipped with the transmitter.

Checking the density or temperature reading
View the flowmeter density or temperature measurement in any of several ways:
- Use the transmitter display, if it has one
- Use a HART Communicator, ProLink or ProLink II software, or AMS software
- Use the connected output device, if there is one

• Use the host controller

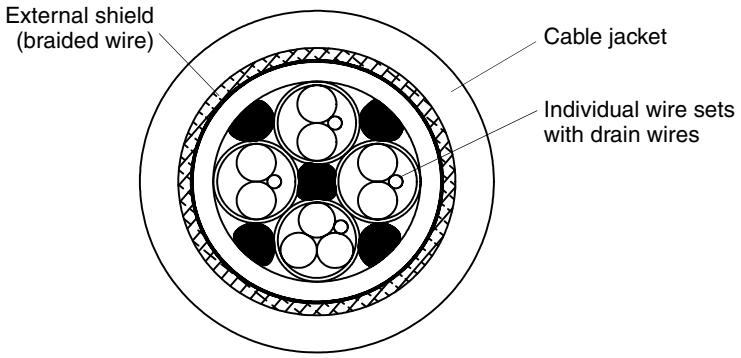
If necessary, test the process fluid to confirm the flowmeter measurement is correct.

Checking for RF or transient-voltage interference
Radio-frequency (RF) or transient-voltage interference can affect the input or output signals at the transmitter. If you suspect interference, and can eliminate the source, do so before checking the alternatives described below.

Output wiring. Output wiring can be affected by interference. Make sure output wiring from the transmitter is properly grounded in accordance with the instructions in the transmitter manual. Also make sure no wires remain exposed at either end of output wiring.

Flowmeter cable. If the flowmeter cable does not have an external shield (see illustration, below), and is not installed in conduit, it could be affected by interference. Also make sure no wires remain exposed at either end of the flowmeter cable.

Cross-section of externally shielded cable



Troubleshooting at the sensor

The tables in the preceding sections refer you to this section for instructions on troubleshooting at the sensor. To troubleshoot at the sensor, you might need a digital multimeter (DMM) or similar device. For some procedures, you might also need the transmitter manual.

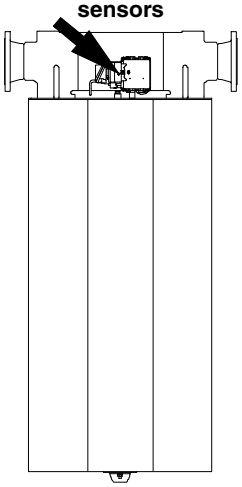
Checking flowmeter grounding
The sensor can be grounded via the piping, as long as joints in the pipeline are ground-bonded, or by means of a ground screw on the sensor case. See illustration, below. Transmitter grounding is described in the transmitter instruction manual.

If the sensor is not grounded via the piping, and if national standards are not in effect, adhere to these guidelines to ground the sensor via the junction box:
• Use copper wire, 14 AWG (2,5 mm^2) or larger wire size for grounding.
• Keep all ground leads as short as possible, less than 1 ohm impedance.
• Connect ground leads directly to earth, or follow plant standards.

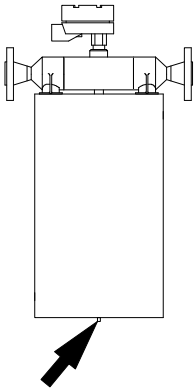
For hazardous area installation in Europe, use standard EN 60079-14 as a guideline if national standards are not in effect.

Sensor grounding screw

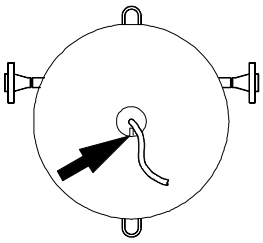
Model D600 sensors



Other Model D sensors



Model DT sensors



Checking for moisture in the core processor or sensor junction box
Note that the following will help reduce the risk of getting moisture in the core processor or sensor junction box: If possible, install wiring with the conduit openings pointed down to reduce the risk of condensation or moisture in the housing. Otherwise, install drip legs on the cable or conduit.

All wiring compartments must be sealed to prevent a short circuit. A short would result in measurement error or flowmeter failure.
- The D600 has a junction box and a booster amplifier housing.
- Do not open the D600 booster amplifier housing while the booster amplifier is energized. See the warning statement below.
- Replace all covers and seal all openings before applying power to a D600 sensor.

⚠ WARNING

Explosion Hazard

In a hazardous area:
- Do not open booster amplifier housing cover while booster amplifier is energized.
- Wait at least 30 minutes after power is shut off before opening.

Open the junction box (and, for a D600, the booster amplifier housing) to check for moisture. If moisture is present, dry out the junction box. Do not use contact cleaner. Follow these guidelines to avoid risk of condensation or excessive moisture from accumulating:
• Seal all conduit openings.
• Install drip legs in conduit or cable.
• If possible, install wiring with junction-box openings pointed down.
• Check integrity of gaskets.
• Close and fully seal all housing covers.

Checking for mounting stress on the sensor
Because each installation is unique, it is not possible to offer a definitive solution for mounting problems. However, mounting stresses can be caused by one or more of the following conditions:
• The pipeline is being supported by (hung from) the sensor.
• Misaligned piping was drawn together by the sensor.
• An unsupported pipeline is not sturdy enough to support the sensor.

If you are unable to determine whether the process connections are being subjected to mounting stress, contact Micro Motion for additional assistance. Phone numbers are listed on page 41.

Checking for vibration and crosstalk
Micro Motion sensors have been designed to minimize the effect of vibration. In very rare cases, however, vibration or crosstalk can affect flowmeter operation. *Crosstalk* is the transfer of resonant vibration from one sensor to another, and sometimes occurs when two like-size sensors are installed in close proximity to each other and are operating on the same fluid for short periods of time.

Micro Motion meters are rarely affected by vibration, so vibration or crosstalk is probably not the problem. If you are not sure whether vibration or crosstalk is affecting the sensor, contact Micro Motion for additional assistance. Phone numbers are listed on page 41.

Checking for 2-phase flow
Two-phase flow occurs when air or gas is present in a liquid process stream, or when liquid is present in a gas process stream. Two-phase flow has several causes, as described below.

Leaks. Leaks can occur at process connections, valve seals, and pump seals, resulting in air being introduced into a liquid stream. Air might also be drawn in at the system inlet. Check the system for leaks, and repair any leaks that are found.

Cavitation and flashing. Cavitation and flashing are caused by operating the system at or near the process fluid vapor pressure, resulting in pockets of air or gas being introduced into the process fluid. If the sensor is near a device that causes pressure drop, such as a control valve, locating the sensor upstream from the device can decrease the risk of flashing. Alternatively, increasing back pressure downstream from the sensor can also reduce the risk of cavitation and flashing.

Cascading. Cascading of the fluid can occur when the flow rate diminishes to the point where the sensor tube is only partially filled.

Often, this occurs because fluid is flowing downward through a sensor installed in a vertical pipeline. (When a sensor is mounted this way, it is called the flag-mount orientation).

To help eliminate cascading, fluids should flow upward through a flag-mounted sensor. Mounting the sensor in the preferred orientation often reduces cascading. (See *Orientation*, page 13.) Increasing back pressure downstream from the sensor can also reduce or eliminate cascading.

High points in the system. When measuring liquids, *entrained air* (pockets of non-condensable gas) can collect in high points of a fluid system. If the fluid velocity is low, and/or the high points are very high relative to the system, entrained air pockets can grow and persist. If the air pocket releases and passes through the sensor, measurement error could occur. One possible solution is to install vent valves or air eliminators at a high point in the system, upstream from the sensor. Use your common plant practices if you choose to install vent valves or air eliminators.

Low points in the system. When measuring gases, liquid condensate can collect in low points of a fluid system. If the fluid velocity is low, and/or the low points are very low relative to the system, condensates can accumulate and persist. If the liquid passes through the sensor, measurement error could occur. One possible solution is to install condensate valves at a low point in the system, upstream from the sensor. Use your common plant practices if you choose to install condensate valves.

Checking for plugging or build-up

If the process fluid tends to build up in the piping, the sensor can become plugged or partially plugged due to build-up of material inside the sensor flow tubes. To determine whether plugging or build-up has occurred, check at the transmitter for a high drive gain and high density reading (see page 50).

- If the drive gain and the density reading are both high, flush or clean the sensor, then check for an accurate density reading on water (or some other fluid with a known density). If the density is still wrong, plugging of the tube is probably not the problem.
- If either the drive gain or the density reading is not high, plugging of the tube is probably not the problem.

Appendix
A

Purge Fittings

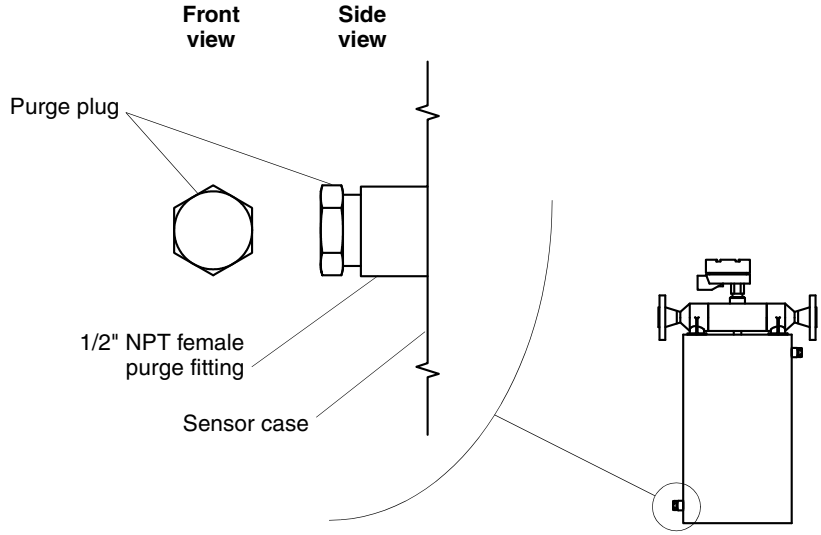
Keeping purge fittings sealed

If the sensor has purge fittings, they should remain sealed at all times. After a purge plug is removed, the sensor case should be purged with a dry, inert gas (such as argon or nitrogen), and resealed. See *Case purging procedure*, page 56.

Purging the case protects internal components. Before Micro Motion ships a sensor from the factory, it purges the sensor case. If you never loosen or remove the fittings, you do not have to be concerned about them.

For more information, contact the Micro Motion Customer Service Department:
- In the U.S.A., phone **1-800-522-MASS** (1-800-522-6277), 24 hours
- In Canada and Latin America, phone +1 303-527-5200 (U.S.A.)
- In Asia, phone +65 6777-8211 (Singapore)
- In the U.K., phone 0870 240 1978 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 555 (The Netherlands)
- Or visit our website at **www.micromotion.com**.

Purge fittings



Using purge fittings

The primary reason for having purge fittings is to monitor pressure inside the sensor case. Some users, such as those measuring highly volatile fluids, install a pressure transmitter across the sensor purge fittings. A control device, connected to the pressure transmitter, shuts down the process if a change in pressure is detected. This provides additional protection should a rupture occur inside the sensor.

Removing a purge plug

If you remove a purge plug from the sensor case, it is necessary to re-purge the case.

⚠ WARNING

Removing a purge plug will require the sensor case to be re-purged with a dry inert gas. Improper pressurization could result in serious personal injury.

Follow all instructions for re-purging the sensor case. See *Case purging procedure*, below.

Case purging procedure

Read all instructions before performing the case purging procedure. It is not necessary to perform this procedure unless a purge plug has been removed.

1. Shut down the process, or set control devices for manual operation.

⚠ CAUTION

Performing the purge procedure while the flowmeter is operating could affect measurement accuracy, resulting in inaccurate flow signals.

Before performing the case purging procedure, shut down the process, or set control devices for manual operation.

2. Remove both purge plugs from the sensor case. If purge lines are being used, open the valve in the purge lines.

3. Connect the supply of dry, inert gas to the inlet purge connection or open inlet purge line. Leave the outlet connection open.
   - Exercise caution to avoid introducing dirt, moisture, rust, or other contaminants into the sensor case.
   - If the purge gas is heavier than air (such as argon), locate the inlet lower than the outlet, so the purge gas will displace air from bottom to top.
   - If the purge gas is lighter than air (such as nitrogen), locate the inlet higher than the outlet, so the purge gas will displace air from top to bottom.

4. Make sure there is a tight seal between the inlet connection and sensor case, so air cannot be drawn by suction into the case or purge line.

5. The purge time is the amount of time required for full exchange of atmosphere to inert gas. For each sensor size, the purge time is different. Refer to the table below. If purge lines are being used, increase the purge time to fill the additional volume of the purge line.

6. Avoid pressurizing the sensor case. At the appropriate time, shut off the gas supply, then immediately seal the purge outlet and inlet connections. If pressure inside the case elevates above atmospheric pressure during operation, the flowmeter density calibration will be inaccurate.

Time required to purge Model D sensor cases

Sensor model	**Purge rate** *cubic ft/hr (l/hr)*	**Time*** *minutes*
D25	20 (566)	3
D38	20 (566)	3
D40	20 (566)	3
D65	20 (566)	10
D100	20 (566)	15
D150	20 (566)	15
D300	40 (1132)	30
D600	80 (2264)	60

* If purge lines are being used, increase purge time to fill the additional volume.

Appendix
B

Rupture Disk

Using the rupture disk

The primary reason for having a rupture disk is to vent process fluid from inside the sensor case, should the sensor flow tube rupture in a high-pressure application. Some users, such as those measuring high-pressure gases, install a pipeline at the rupture disk fitting, to help contain escaping process fluid. This provides additional protection should a rupture occur.

⚠ WARNING

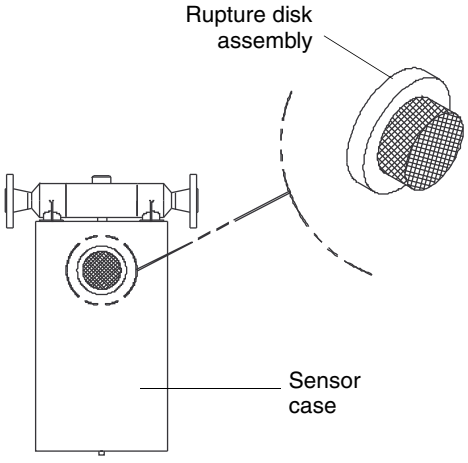
Pressure Relief Zone.

Escaping high-pressure fluid can cause severe injury or death.

Stay clear of rupture disk pressure-relief area.

For more information, contact the Micro Motion Customer Service Department:
- In the U.S.A., phone 1-800-522-MASS (1-800-522-6277), 24 hours
- In Canada and Latin America, phone +1 303-527-5200 (U.S.A.)
- In Asia, phone +65 6777-8211 (Singapore)
- In the U.K., phone 0870 240 1978 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 555 (The Netherlands)
- Or visit our website at **www.micromotion.com**.

Rupture disk



Appendix
C

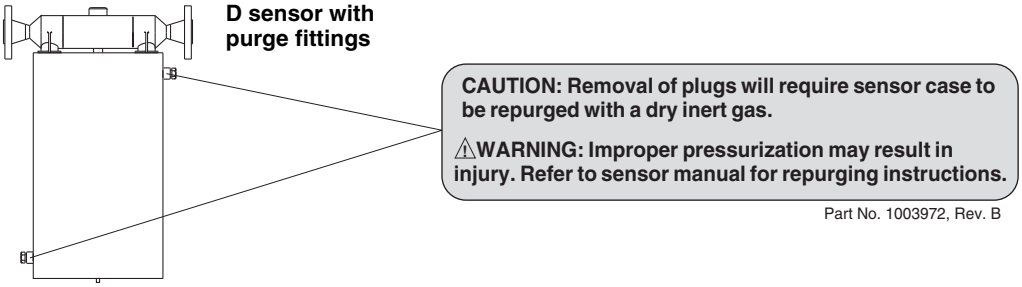
Label Maintenance and Replacement

Maintaining and replacing labels

Micro Motion product safety labels have been designed in accordance with the voluntary standard, ANSI Z535.4. If any of the labels illustrated below is illegible, damaged, or missing, promptly have a new one installed. The sensor includes the safety labels illustrated below.

Contact Micro Motion for replacement labels:
- In the U.S.A., phone 1-800-522-MASS (1-800-522-6277), 24 hours
- In Canada and Latin America, phone +1 303-527-5200 (U.S.A.)
- In Asia, phone +65 6777-8211 (Singapore)
- In the U.K., phone 0870 240 1978 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 555 (The Netherlands)
- Or visit our website at **www.micromotion.com**.

Label number 1003972


D sensor with purge fittings
CAUTION: Removal of plugs will require sensor case to be repurged with a dry inert gas.
⚠WARNING: Improper pressurization may result in injury. Refer to sensor manual for repurging instructions.

Part No. 1003972, Rev. B

For additional information, see *Removing a purge plug* and *Case purging procedure*, page 56.

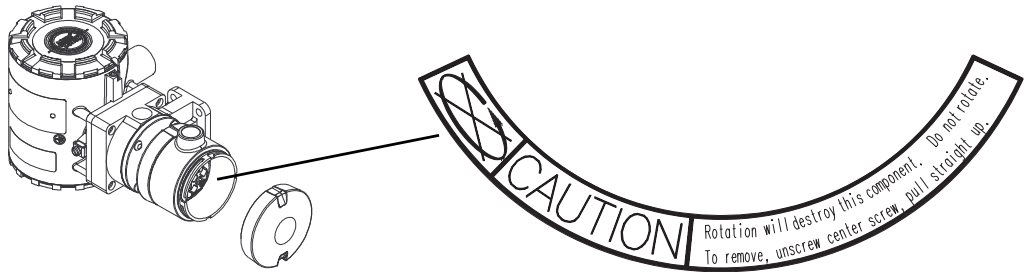
Label number 1004570

Part No. 1004570

Label number 1004134

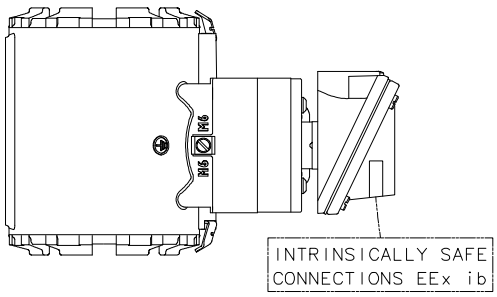
For additional information, see Appendix B, page 59.

Label number 3600460

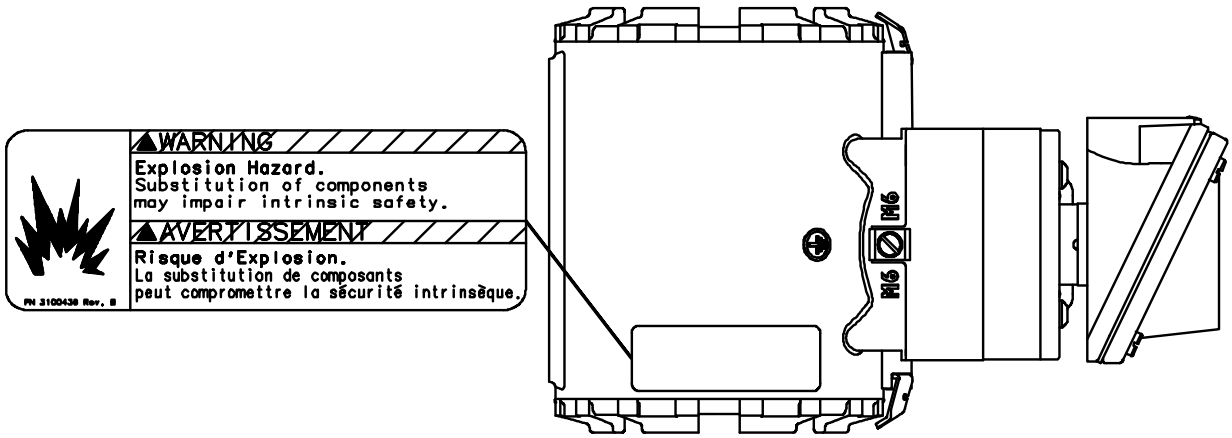


(label inside core processor housing)

Label number 3005784



Label number 3100436



Appendix
D

Return Policy

General guidelines

Micro Motion procedures must be followed when returning equipment. These procedures ensure legal compliance with government transportation agencies and help provide a safe working environment for Micro Motion employees. Failure to follow Micro Motion procedures will result in your equipment being refused delivery.

Information on return procedures and forms is available on our web support system at **www.micromotion.com**, or by phoning the Micro Motion Customer Service department.

New and unused equipment

Only equipment that has not been removed from the original shipping package will be considered new and unused. New and unused equipment requires a completed Return Materials Authorization form.

Used equipment

All equipment that is not classified as new and unused is considered used. This equipment must be completely decontaminated and cleaned before being returned.

Used equipment must be accompanied by a completed Return Materials Authorization form and a Decontamination Statement for all process fluids that have been in contact with the equipment. If a Decontamination Statement cannot be completed (e.g., for food-grade process fluids), you must include a statement certifying decontamination and documenting all foreign substances that have come in contact with the equipment.

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EMERSON™
Process Management

Quick Reference Guide
P/N 1005048, Rev. C
June 2003

Micro Motion® Model D600 Sensor

Installation Instructions

For online technical support, use the EXPERT$_2$™ system at www.expert2.com. To speak to a customer service representative, call the support center nearest you:

- In the U.S.A., phone 1-800-522-MASS (1-800-522-6277)
- In Canada and Latin America, phone (303) 530-8400
- In Asia, phone (65) 6770-8155
- In the U.K., phone 0800 - 966 180 (toll-free)
- Outside the U.K., phone +31 (0) 318 495 670

Micro Motion™ — EMERSON™ Process Management

BEFORE YOU BEGIN

This quick reference guide explains basic installation guidelines for Micro Motion® Model D600 sensors. For detailed information, refer to the instruction manual that was shipped with the sensor.

European installations

This Micro Motion product complies with all applicable European directives when properly installed in accordance with the instructions in this quick reference guide. Refer to the EC declaration of conformity for directives that apply to this product.

The EC declaration of conformity, with all applicable European directives, and the complete *ATEX Installation Drawings and Instructions* are available on the internet at www.micromotion.com/atex or through your local Micro Motion support center.

INTRODUCTION

The sensor and booster amplifier make up one part of a Coriolis flowmeter. The other part is a transmitter.

Installation options

The sensor and booster amplifier are available in any of the configurations described in Table 1. Table 1 also lists the transmitters that can be used with each configuration.

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Table 1. D600 configurations and compatible transmitters

D600 sensor configuration			
Booster amplifier location	**Booster amplifier wiring component**	**Connection to transmitter**	**Compatible transmitters**
Integral to sensor	Junction box	9-wire	• Model 1700/2700 (with integral core processor) • Model 3500/3700 (9-wire) • RFT9739 • RFT9712 • Remote core processor
	Core processor	4-wire	• Model 1700/2700 • Model 3500/3700 (MVD) • Model 2500 • Direct host(1)
Remote from sensor	Junction box	9-wire	• Model 1700/2700 (with integral core processor) • Model 3500/3700 (9-wire) • RFT9739 • RFT9712 • Remote core processor
	Core processor	4-wire	• Model 1700/2700 • Model 3500/3700 (MVD) • Model 2500 • Direct host(1)

(1) A direct host is a user-supplied remote controller, PLC, or other device.

The following figures illustrate these different configurations:

- Figure 1 shows the complete D600 sensor with an integral booster amplifier and junction box.
- Figure 2 shows the D600 sensor with an integral booster amplifier and core processor.
- Figure 3 shows the D600 sensor with junction boxes for connecting to a remote booster amplifier.
- Figure 4 shows two remote booster amplifiers, one with a junction box and one with a core processor.

Figure 1. D600 sensor with integral booster amplifier and junction box

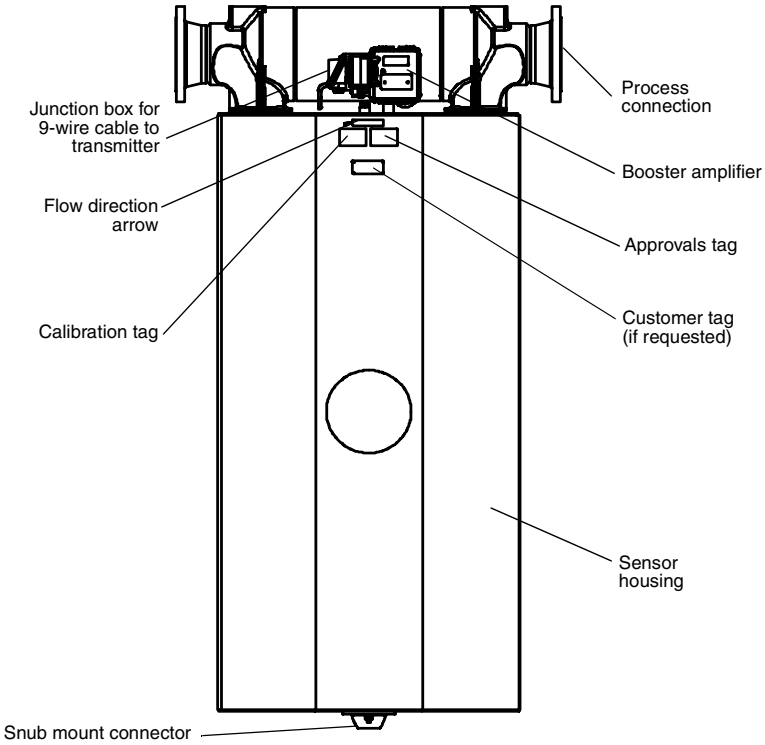


Figure 2. D600 sensor with integral booster amplifier and core processor

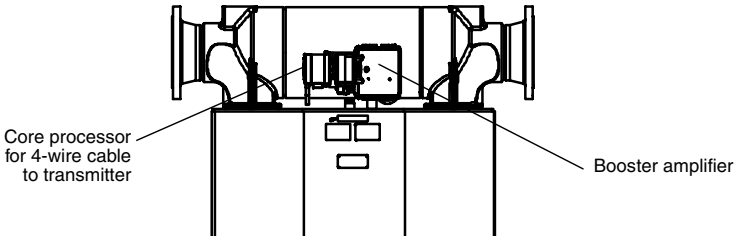


Figure 3. D600 sensor with junction boxes for remote booster amplifier

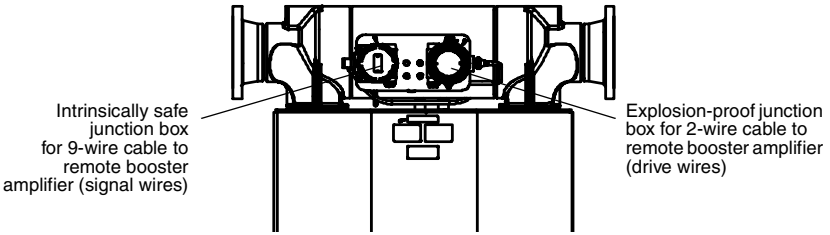
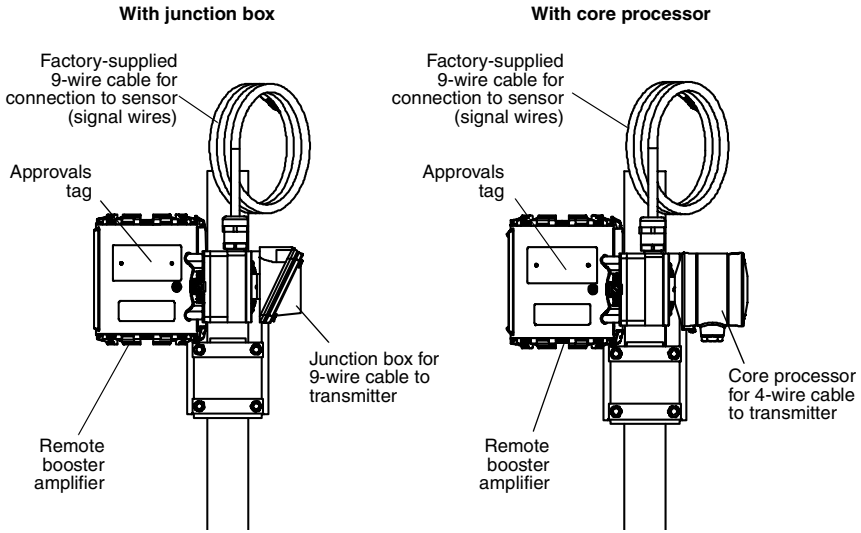

Intrinsically safe junction box for 9-wire cable to remote booster amplifier (signal wires)
Explosion-proof junction box for 2-wire cable to remote booster amplifier (drive wires)

Figure 4. Remote booster amplifier


With junction box
Factory-supplied 9-wire cable for connection to sensor (signal wires)
Approvals tag
Junction box for 9-wire cable to transmitter
Remote booster amplifier
With core processor
Factory-supplied 9-wire cable for connection to sensor (signal wires)
Approvals tag
Core processor for 4-wire cable to transmitter
Remote booster amplifier

STEP 1. Choosing a location

Choose a location for the sensor based on the requirements described in this section.

General guidelines

The following conditions must be met:

- Before operation, you must be able to stop flow through the sensor. (During the zeroing procedure, flow must be stopped completely, and the sensor must be full of process fluid.)
- During operation, the sensor must remain full of process fluid.
- The sensor must be installed in an area that is compatible with the classification specified on the sensor approvals tag (see Figure 1 and Figure 4).

Hazardous area installations

Make sure the hazardous areas specified on the approvals tags are suitable for the environment in which the sensor and booster amplifier will be installed. See Figures 1 and 4. For installation in an area that requires intrinsic safety, refer to Micro Motion UL, CSA, or ATEX documentation, shipped with the sensor or available from the Micro Motion web site.

For a complete list of hazardous area classifications for Micro Motion sensors, refer to the EXPERT$_2$™ system at www.expert2.com.

Environmental limits

Temperature limits for the D600 sensor and booster amplifier are listed in Table 2.

Table 2. D600 temperature limits

Component	Temperature limits
Sensor with integral booster amplifier(1)	–58 to +140 °F (–50 to +60 °C)
Sensor with remote booster amplifier(1)	–400 to +400 °F (–240 to +204 °C)
Remote booster amplifier(2)	–40 to +140 °F (–40 to +60 °C)

(1) Limits apply to process fluid temperature.
(2) Limits apply to ambient temperature.

Process fluid temperature and ambient temperature can be further restricted by approvals. For detailed information, see the sensor's calibration tag.

Sensor-to-remote booster amplifier cable lengths

Remote booster amplifiers are shipped with:

- 16 feet (5 meters) of 9-wire cable for connection to the sensor's intrinsically safe junction box
- 16 feet (5 meters) of 2-wire cable for connection to the sensor's explosion-proof junction box (not available in all locations)

For longer cable lengths, up to 60 feet (20 meters), contact Micro Motion.

Sensor-to-transmitter cable lengths

Maximum cable length between sensor and transmitter depends on the cable type. See Table 3.

Table 3. Maximum cable lengths

Cable type	Wire gauge	Maximum length
Micro Motion 9-wire	Not applicable	
• to Model 1700/2700		60 feet (20 meters)
• to remote core processor		60 feet (20 meters)
• to Model 3500/3700 (9-wire)		1000 feet (300 meters)
• RFT9739		1000 feet (300 meters)
• RFT9712		1000 feet (300 meters)
Micro Motion 4-wire	Not applicable	1000 feet (300 meters)
User-supplied 4-wire		
• Power wires (VDC)	22 AWG (0,35 mm^2)	300 feet (90 meters)
	20 AWG (0,5 mm^2)	500 feet (150 meters)
	18 AWG (0,8 mm^2)	1000 feet (300 meters)
• Signal wires (RS-485)	22 AWG (0,35 mm^2) or larger	1000 feet (300 meters)

Sensor-to-core processor cable length

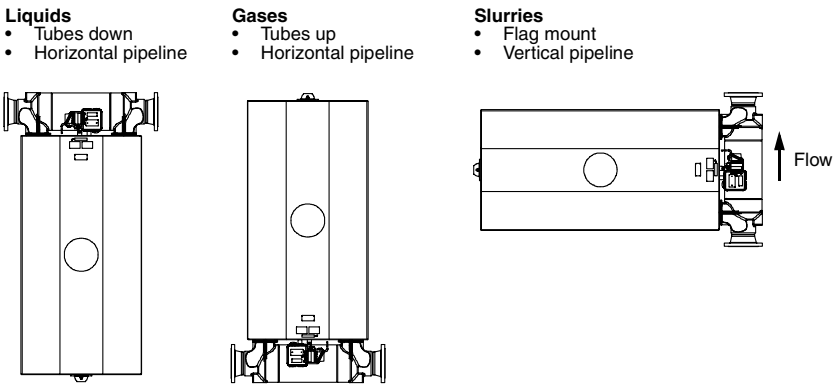
Maximum distance between the sensor and the core processor is 60 feet (20 meters). If you are using a remote booster amplifier with a junction box, connecting to a remote core processor, the combined length of the two 9-wire cables (sensor-to-booster amplifier and booster amplifier-to-core processor) must be 60 feet (20 meters) or less.

STEP 2. Orienting the sensor

The sensor will function properly in any orientation if the sensor tubes remain filled with process fluid. Micro Motion recommends installing the sensor according to the type of process fluid and the flow direction:

- Preferred orientations are shown in Figure 5.
- The sensor has a flow direction arrow (see Figure 1) to help you configure the transmitter for flow direction. If possible, install the sensor so that the flow direction arrow matches actual process flow.

Figure 5. Preferred orientations



STEP 3. Mounting the sensor

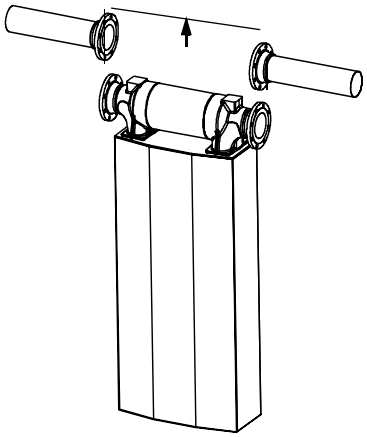
⚠ CAUTION

Using the sensor to support piping can damage the meter or cause measurement error.

Do not use flowmeter to support pipe.

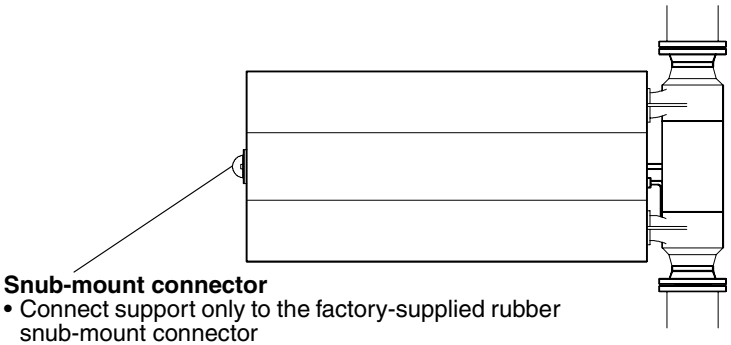
Use your common practices to minimize torque and bending load on process connections. Figure 6 illustrates how to mount the D600 sensor. If possible, install wiring with the conduit opening pointed down to reduce the risk of condensation or excessive moisture.

Figure 6. Mounting the sensor



For installation in a vertical pipeline (flag-mount orientation), the D600 has a snub connector to provide added support in high-vibration installations. See Figure 7.

Figure 7. Optional added support for sensor in flag-mount orientation



Snub-mount connector
- Connect support only to the factory-supplied rubber snub-mount connector
- Attach with 1/2"-13 UNC bolt
- Bolt may penetrate isolator to 1 1/2" (40 mm)

STEP 4. Wiring the booster amplifier

⚠ CAUTION

Improper installation of wiring could cause measurement error or sensor failure.

- Shut off power before installing power-supply wiring.
- Follow all instructions to ensure sensor will operate correctly.
- Install drip legs in conduit or cable.
- Seal all conduit openings.
- Ensure integrity of gaskets, grease all O-rings, and fully tighten sensor junction-box cover, booster amplifier cover, core processor cover, and all transmitter housing covers.

⚠ WARNING

Improperly removing the booster amplifier housing cover in a hazardous area could cause an explosion.

In a hazardous area:

- Do not open booster amplifier housing cover while booster amplifier is energized.
- Wait at least 30 minutes after power is shut off before opening.

Power supply wiring to the booster amplifier

The booster amplifier, whether mounted integrally or remotely with the D600 sensor, requires a separate AC power supply. To wire the booster amplifier power supply:

1. Remove screw and terminal cover before installing wiring. Grease O-ring and re-install cover before operating.
2. Provide 85-250 VAC power to terminal N/L2 and terminal L/L1.
   - For integral booster amplifier wiring, see Figure 8.
   - For remote booster amplifier wiring, see Figure 9.

3. Connect the ground wire for the power supply to the internal ground screw.

   This unit is also provided with an external ground screw for use where local codes or authorities permit or require such connections.

Figure 8. Power supply wiring for integral booster amplifier

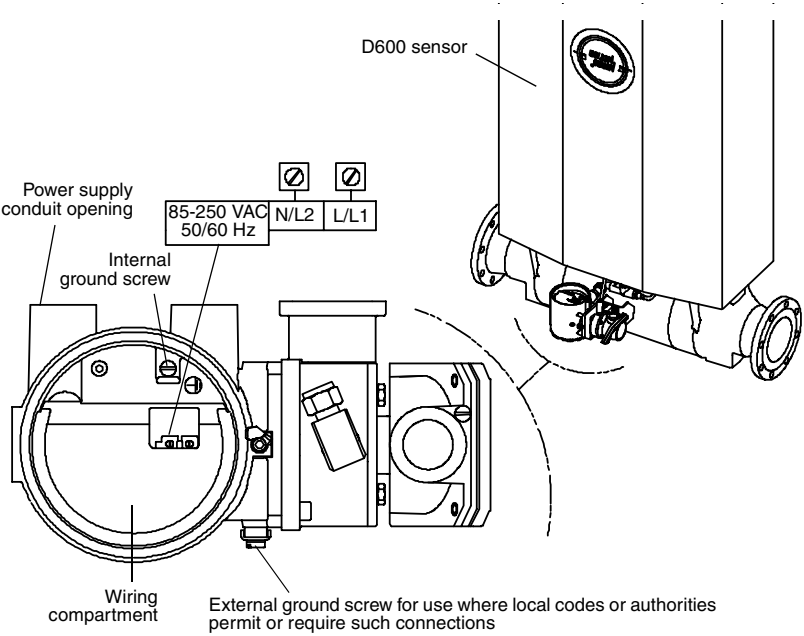
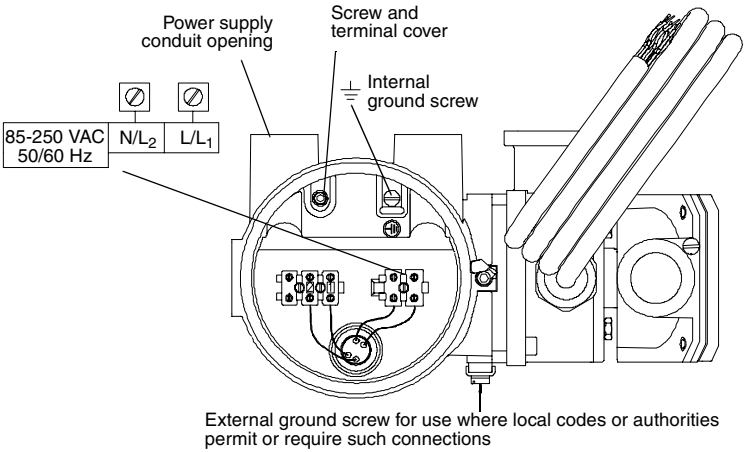

D600 sensor
Power supply conduit opening
85-250 VAC 50/60 Hz
N/L2
L/L1
Internal ground screw
Wiring compartment
External ground screw for use where local codes or authorities permit or require such connections

Figure 9. Power supply wiring for remote booster amplifier


Power supply conduit opening
Screw and terminal cover
Internal ground screw
85-250 VAC 50/60 Hz
N/L2
L/L1
External ground screw for use where local codes or authorities permit or require such connections

Wiring from the remote booster amplifier to the sensor

The remote version of the booster amplifier requires connection of two cables from the booster amplifier to the junction boxes on the sensor:

- 9-wire cable (signal wires) — This cable is supplied by Micro Motion, and is pre-attached to the booster amplifier.
- 2-wire cable (drive wires) — In some locations, this cable may be supplied by Micro Motion. If the cable is not supplied, use twisted-pair 18 AWG (0,75 mm^2) 2-wire cable.

To connect the 9-wire cable (signal wires):

1. Do not modify connections at the booster amplifier.
2. Do not place the 9-wire cable and 2-wire cable in the same cable tray.
3. At the sensor end of the 9-wire cable (see left side of Figure 10):
   a. Clip all four drain wires and leave them disconnected.
   b. Clip the red and brown wires and insulate them.
   c. Matching by color, connect the remaining wires (except for the orange wire) to the corresponding terminals from the sensor feedthrough.
   d. The orange wire in the cable does not have a corresponding orange wire from the sensor. Connect the orange wire to the terminal indicated in Figure 10.
   e. Terminate the cable braid inside the cable gland.

To connect the 2-wire cable (drive wires):

1. Use twisted-pair 18 AWG (0,75 mm^2) 2-wire cable. Ensure that the cable is shielded, continuous from the booster amplifier to the sensor's explosion-proof junction box. Two methods can be used:
   - Metallic conduit
   - Shielded or armored cable (do not place the 2-wire cable and 9-wire cable in the same cable tray)
2. Connect the wires:
   a. Connect terminal 1 at the sensor (see Figure 10) to terminal 1 at the booster amplifier (see Figure 11).
   b. Connect terminal 2 at the sensor to terminal 2 at the booster amplifier.
3. If the cable has a drain wire:
   a. At the sensor end, clip the drain wire and leave it disconnected.
   b. At the booster amplifier end, connect the drain wire to the internal ground screw. See Figure 11.
4. If the cable has a braid, terminate it in the cable gland at both ends.

Figure 10. Sensor junction boxes for remote booster amplifier

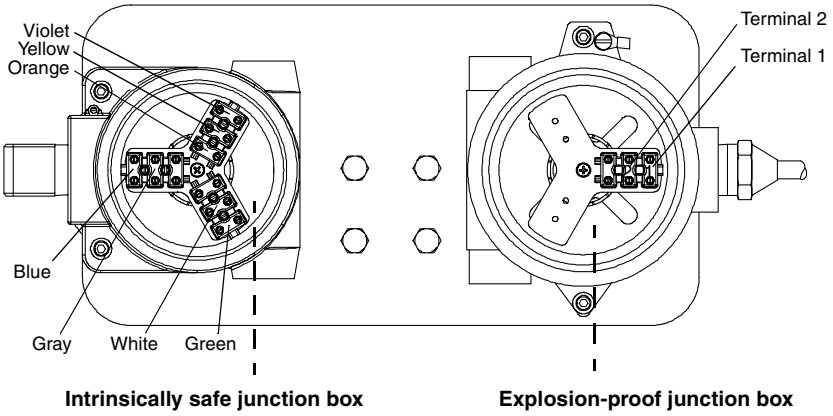
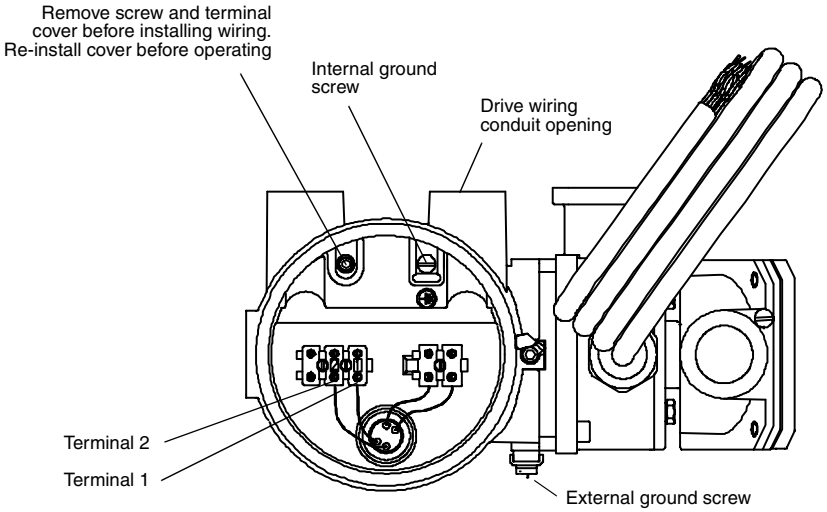


Figure 11. Remote booster amplifier – 2-wire cable (drive wires)


Remove screw and terminal cover before installing wiring. Re-install cover before operating
Internal ground screw
Drive wiring conduit opening
Terminal 2
Terminal 1
External ground screw

STEP 5. Wiring the sensor to the transmitter or direct host

⚠ WARNING

Failure to comply with requirements for intrinsic safety in a hazardous area could result in an explosion.

- For installation in an area that requires intrinsic safety, refer to Micro Motion UL, CSA, or ATEX documentation, shipped with the sensor or available from the Micro Motion web site.
- For hazardous area installations in Europe, refer to standard EN 60079-14 if national standards do not apply.

⚠ CAUTION

Failure to seal sensor and transmitter housings could cause a short circuit, which would result in measurement error or flowmeter failure.

- Ensure integrity of gaskets and O-rings.
- Grease all O-rings before sealing.
- If conduit is used, install drip legs in conduit.
- Seal all conduit openings.

⚠ CAUTION

Allowing the shield drain wires to contact the sensor junction box can cause flowmeter errors.

Do not allow the shield drain wires to contact the sensor junction box.

Junction box to 9-wire transmitter

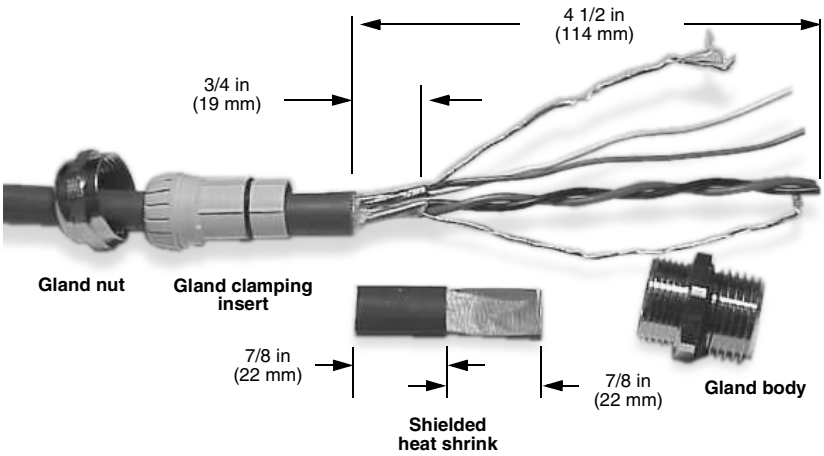
If connecting from a D600 sensor with an integral booster amplifier and junction box (see Figure 1) or from a remote booster amplifier with a junction box (see the left side of Figure 4), follow the steps below to connect the 9-wire cable between the junction box and the transmitter.

1. Prepare and install the cable according to the instructions in Micro Motion's *9-Wire Flowmeter Cable Preparation and Installation Guide*.
2. Insert the stripped ends of the individual wires into the terminal blocks. No bare wires should remain exposed.
3. Match the wires color for color. For wiring at the transmitter, see the transmitter *Quick Reference Guide*.
4. Tighten the screws to hold the wires in place.
5. Ensure integrity of gaskets, grease all O-rings, then tightly close and seal the junction box cover and all housing covers on the transmitter.

Core processor to 4-wire transmitter or direct host

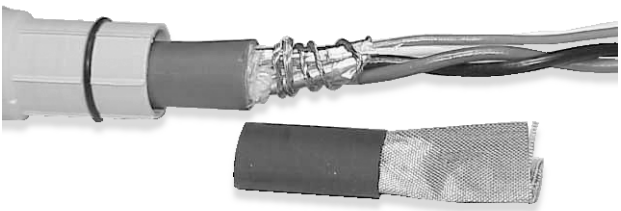
If connecting from a D600 sensor with an integral booster amplifier and core processor (see Figure 2) or from a remote booster amplifier with a core processor (see the right side of Figure 4), follow the steps below to connect the 4-wire cable between the core processor and the transmitter or direct host.

1. Use one of the following methods to shield the wiring:
   - If you are installing unshielded wiring in continuous metallic conduit that provides 360° termination shielding for the enclosed wiring, go to Step 6.
   - If you are installing a user-supplied cable gland with shielded cable or armored cable, terminate the shields in the cable gland. Terminate both the armored braid and the shield drain wires in the cable gland. Go to Step 6.
   - If you are installing a Micro Motion-supplied cable gland at the core processor housing:
     - Prepare the cable and apply shielded heat shrink as described below. The shielded heat shrink provides a shield termination suitable for use in the gland when using cable whose shield consists of foil and not a braid. Proceed to Step 2.
     - With armored cable, where the shield consists of braid, prepare the cable as described below, but do not apply heat shrink. Proceed to Step 2.
2. Remove the cover from the core processor.
3. Slide the gland nut and the clamping insert over the cable.



4. For connection at the core processor housing, prepare shielded cable as follows (for armored cable, omit steps d, e, f, and g):
   a. Strip 4 1/2 inches (114 mm) of cable jacket.
   b. Remove the clear wrap that is inside the cable jacket, and remove the filler material between the wires.
   c. Remove the foil shield that is around the insulated wires, leaving 3/4 inch (19 mm) of foil or braid and drain wires exposed, and separate the wires.
   d. Wrap the shield drain wire(s) around the exposed foil twice. Cut off the excess wire.

Shield drain wire(s) wrapped twice around exposed shield foil

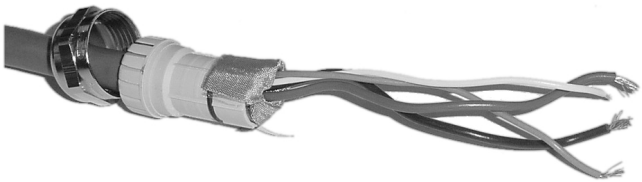


   e. Place the shielded heat shrink over the exposed shield drain wire(s). The tubing should completely cover the drain wires.
   f. Without burning the cable, apply heat (250 °F or 120 °C) to shrink the tubing.

Shielded heat shrink completely covers exposed drain wires

g. Position gland clamping insert so the interior end is flush with the heat shrink.

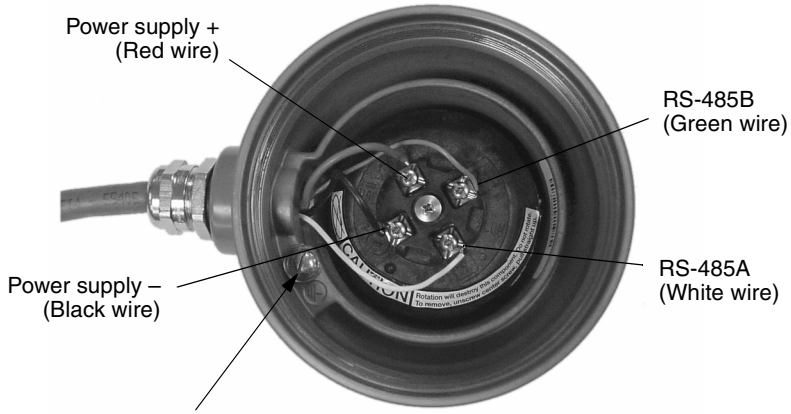
h. Fold the cloth shield or braid and drain wires over the clamping insert and approximately 1/8 inch (3 mm) past the O-ring.



i. Install the gland body into the core processor housing conduit opening.

5. Insert the wires through the gland body and assemble the gland by tightening the gland nut.
6. Identify the wires in the 4-wire cable. The 4-wire cable supplied by Micro Motion consists of one pair of 18 AWG (0,75 mm^2) wires (red and black), which should be used for the VDC connection, and one pair of 22 AWG (0,35 mm^2) wire (green and white), which should be used for the RS-485 connection. Connect the four wires to the numbered slots on the core processor, matching corresponding numbered terminals on the transmitter. See Figure 12.

Figure 12. Connecting the wires at the core processor



Core processor housing internal ground screw

- For connections to earth ground when core processor cannot be grounded via sensor piping and local codes require ground connections to be made internally
- Do not connect shield drain wires to this terminal

7. Reattach the core processor cover.
8. For wiring at the transmitter, see the transmitter *Quick Reference Guide*.
9. If connecting to a direct host, you must connect the VDC wires from the core processor to a power supply, and you must connect the RS-485 wires to the RS-485 terminals on the host.
    - If you are connecting to an I.S. barrier supplied by Micro Motion (MVD Direct Connect installations), the barrier supplies power to the core processor.
        a. Connect all 4 wires of the 4-wire cable from the core processor to the barrier. Refer to the barrier documentation to identify the terminals at the barrier.
        b. Ensure that there is no electromagnetic interference coupled onto the 4 wires between the core processor and the barrier.

- If you are not using a barrier:
  a. Connect the VDC wires from the core processor (see Figure 12) to an independent power supply. This power supply must connect only to the core processor. A recommended power supply is the SDN series of 24-VDC power supplies manufactured by Sola/Hevi-Duty.
  b. Do not ground either connection of the power supply.
  c. Connect the RS-485 wires from the core processor (see Figure 12) to the RS-485 terminals at the direct host. Refer to the vendor documentation to identify the terminals.
  d. Ensure that there is no electromagnetic interference coupled onto the cables between the core processor and the power supply or direct host.

STEP 6. Grounding the sensor

⚠ CAUTION

Improper grounding could cause measurement error.

To reduce the risk of measurement error:

- Ground the flowmeter to earth, or follow ground network requirements for the facility.
- For hazardous area installations in Europe, refer to standard EN 60079-14 if national standards do not apply.

The sensor must be grounded. The sensor may be grounded via the piping if the joints in the pipeline are ground-bonded. If the sensor is not grounded via the piping, connect a ground wire to the sensor ground screw.

If using an integral booster amplifier, it is grounded with the sensor. If using a remote booster amplifier, it must be grounded separately, using the internal or external ground screw as required.

If national standards are not in effect, follow these guidelines to ground the sensor and remote booster amplifier via the provided ground screws:

- Use copper wire, 14 AWG (2,5 mm²) or larger wire size, for grounding.
- Keep ground leads as short as possible.
- Use less than 1 ohm impedance for ground leads.
- Connect ground leads directly to earth, or follow plant guidelines.

For instructions on grounding the transmitter, see the transmitter *Quick Reference Guide*.

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